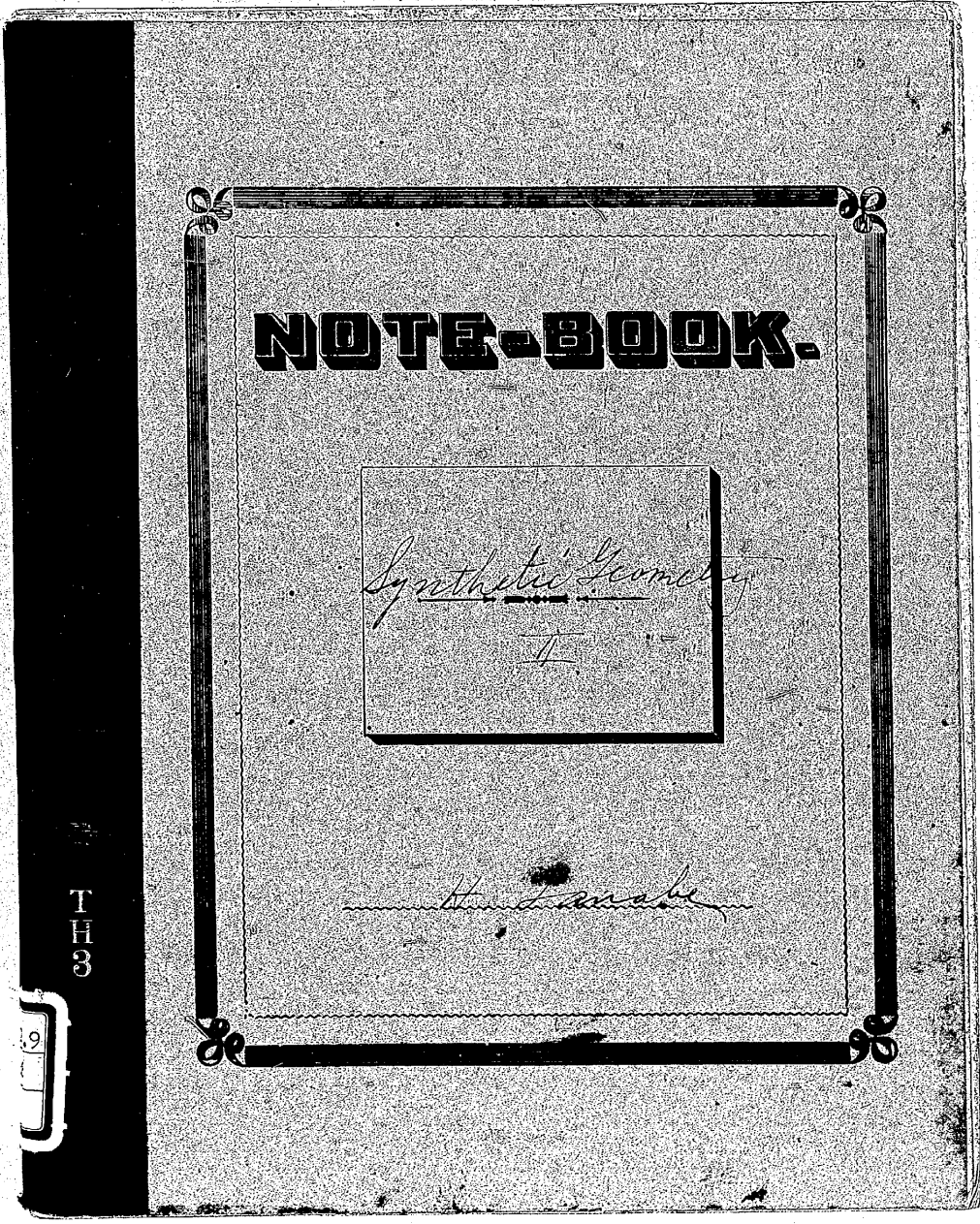


0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24



**NOTE-BOOK.**

*Synthetic Geometry*

*H. H. ...*

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tc121.9  
Ta83  
9

Theorem 2  $V_1, V_2, \dots$  are involutions  $\Rightarrow V_1 V_2 \dots V_n$  is involutory  $\Leftrightarrow$  the product of an even number of involutions is commutative.

Proof  $V_1 V_2 = V_2 V_1$   
 $(V_1 V_2)^2 = V_1 V_2 V_2 V_1 = V_1 V_1 V_2 V_2 = I$   
 $= I$  involutory  
 (2)  $V_1 V_2 = V_3$  involutory  $\Rightarrow V_1^2 V_2^2 = V_2^2 V_1^2 = I$   
 $V_1 V_2 V_3 = (V_1 V_2) V_3 = I = V_3^2 = I$   
 $V_2 V_1 = V_2 V_1 V_3 V_3 = V_2 V_1 V_3^2 = V_2 V_1$   
 $= V_2 V_1 V_3 V_3 = V_2^2 V_3^2 = I$   
 $= V_1 V_2$  commutative

Theorem 3 involutory  $V$  is a conjugate of  $A^{-1}$   $\Leftrightarrow$   $A^{-1} A^{-1}$  is involutory  $\Rightarrow$  involutory  $V$  is commutative.

Proof  $V V^{-1} (A A^{-1}) = V (A A^{-1}) = I (A A^{-1}) = A A^{-1}$   
 $(V V^{-1})^2 (A A^{-1}) = (V V^{-1}) (A A^{-1}) = (A A^{-1})$   
 $(V V^{-1})^2 = I$   
 $\Rightarrow V V^{-1}$  is involutory  $\Rightarrow V$  is involutory (2)  
 commutative.

Illustration  
 plane, space, involutions are cyclic groups of order 2.  
 in Euclidean geometry, 1, pp 434-437

Part II

in 2 metrically & projectively.  $i, i^2, \dots, \sqrt{-1}, \dots$  & metrically  
 coord. in  $\mathbb{R}^n$  &  $\mathbb{C}^n$ , figures & analytic:  $\mathbb{R}^n$  &  $\mathbb{C}^n$  - homogeneous coord. in  $\mathbb{P}^n$  - analytic geom. 1.  $\mathbb{P}^1 \sim \mathbb{C}^1 \cup \{\infty\}$   
 in  $\mathbb{R}^2$  &  $\mathbb{C}^2$ : systematic:  $\dots$  Heffter-Kochler,  
 Lehrbuch d. analyt. Geom.  $\dots$  &  $\mathbb{P}^3$  &  $\mathbb{C}^3$  &  $\mathbb{P}^4$  &  $\mathbb{C}^4$   
 Salmon. Conc. Sects. Higher Curves, Sects 9-9  
 3. Dimension  $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$ : proj. geom.  $\dots$   $\mathbb{P}^3$   
 analyt. algebraic curves, algebraic surfaces,  $\dots$   
 in  $\mathbb{R}^3$  &  $\mathbb{C}^3$ :  $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$  proj.  $\dots$  &  $\mathbb{P}^3$  &  $\mathbb{C}^3$  diffe.  
 central proj. geom. in  $\mathbb{P}^3$ : infinitesimal properties  
 & proj. =  $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   
 proj. method in  $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   
 proj. geom.  $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   
 $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$   $\dots$   $\mathbb{P}^3$  &  $\mathbb{C}^3$

Chapter XIII Projective Transformations

of one dimensional forms

5.5. Anharmonic ratio & projectivity

segment length:  $\mathbb{R}^1$  &  $\mathbb{C}^1$ : algebraic analysis

2. Indistinguishability of real variable:  $\mathbb{R}^1$

Def. -  $\mathbb{P}^1$   $\dots$   $\mathbb{P}^1$   $\dots$   $\mathbb{P}^1$   $\dots$   $\mathbb{P}^1$

$A$	$B$	$C$	$D$	$\frac{AD}{BC}$	$\frac{AD}{BC}$	$\dots$
				$\frac{AD}{BC}$	$\frac{AD}{BC}$	$\dots$





Remark: 1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

5.6. Linear transformation

I. proj. v. u, u' in to base, E. fixed pts  
 O, O' in u = A, B, C, X u', E = A', B', C', X'  
 OA = a, O'A' = b' ---  $\frac{b'-a'}{c'-b'} = \frac{b-a}{c-b}$

$$u \begin{matrix} 0 & A & B & C & X \end{matrix} \quad \frac{AB}{BC} = \frac{AX}{XC} = \frac{b-a}{c-b} \cdot \frac{x-a}{c-x}$$

$$u' \begin{matrix} 0' & A' & B' & C' & X' \end{matrix} \quad \frac{A'B'}{B'C'} = \frac{A'X'}{X'C'} = \frac{b'-a'}{c'-b'} \cdot \frac{x'-a'}{c'-x'}$$

$$\frac{b'-a'}{c'-b'} = \frac{x'-a'}{c'-x'} = \frac{b-a}{c-b} \cdot \frac{x-a}{c-x}$$

$$x' = \frac{\lambda x + \mu}{\nu x + \rho}$$

$\lambda, \mu, \nu, \rho \dots$  constant  $\Rightarrow x, x' = \dots$   
 $x\rho - \nu\mu \neq 0$   
 $x = \frac{x'\rho + \mu}{\nu x' + \rho}$

Ex:  $x' = \frac{x + \mu}{\nu x + \rho}$ ,  $x\rho - \nu\mu \neq 0$

$$a' = \frac{\lambda a + \mu}{\nu a + \rho} \quad b' = \frac{\lambda b + \mu}{\nu b + \rho} \quad c' = \frac{\lambda c + \mu}{\nu c + \rho}$$

$P_x(A'B'C'X') = P_x(A'BC'X)$

These linear transf.  $x' = \frac{\lambda x + \mu}{\nu x + \rho}$   $\lambda\rho - \nu\mu \neq 0$   
 projective 3. 7. 3. 0. necessary & suff. condition  
 proj. group, fundamental theorem

Eq.  $\nu x x' - \lambda x + \rho x' - \mu = 0$   $\lambda\rho - \nu\mu \neq 0$

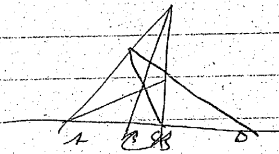
is bilinear form  $\frac{1}{\nu}$  ratio  
 $\lambda, \mu, \nu, \rho$   $\lambda, \mu, \nu, \rho$  4 parameters  
 2 cub.  $\frac{1}{2}x^2$   $\cos^3$  transf. 3. 0. 3. 0. 5.  
 2 linear transf.  $\frac{1}{2}x^2$   $\cos^3$  transf. 3. 0. 3. 0. 5.  
 2 inverse transf. exist  $\Rightarrow$  2 identical transf. exist  
 exist  $\Rightarrow (\mu=0, \nu=0, \frac{1}{\rho} = 1 + s \dots x' = x)$  4  
 linear transf. group  $\mathbb{F}$   $\mathbb{C}$   $\mathbb{R}$  range  
 proj. transf. totalit. continuous group  
 three-termed group  $\mathbb{F}$  (dial.)

proj. double pts. 1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

I. Particular case

ambigu. p. o. = -1 = 1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

$$\frac{AB}{AC} = \frac{AD}{DC}$$



harmonic con.

D is pt at co + ... AD is middle pt. + ...  
affine geom. A = ... pt at co. conj. pt. + middle pt. + ...

VE = involut

bilinear eq.  $x, x' = \dots$

symmetrical  $x, x' = \dots$

$$q - \lambda = p \dots$$

$$v x x' + p(x + x') - q = 0$$

$p^2 + p v \geq 0$   
hyp. ev.  
par. ev.  
ellip. ev.

quadratic eq.

matrix calc. root imaginary

Stand. (imaginary)

Klein Elementar math II  $x, x' = \dots$

Remark proj. g. is Fermion  $x, x' = \dots$

Chales  $x, x' = \dots$  Rouché-Lu

bronar  $x, x' = \dots$  Heurth

Frenth  $x, x' = \dots$  symth geom

$x, x' = \dots$

67. Notion of the theory of invariants (Becary forms)

bilinear H. anf  $x, x' = \dots$

with math. theory of no. quadratic form theory - 194

analysis  $x, x' = \dots$  dif. eq. invariant, automorphic fact.

$x, x' = \dots$  Algebra  $x, x' = \dots$  linear H. anf

$x, x' = \dots$  algebra  $x, x' = \dots$  linear H. anf

invariant theory  $x, x' = \dots$  proj. geom. straight lines

$x, x' = \dots$

3 pt. range  $x, x' = \dots$

$x, x' = \dots$

$$x = \frac{x_1}{x_2} + \dots$$

$(x_1, x_2)$  is pt.  $x$  homogeneous

Coord.  $x, x' = \dots$

42. hom. Coord.  $x, x' = \dots$  finite value  $x, x' = \dots$

$x, x' = \dots$   $x, x' = \dots$  pt. at co.

$x, x' = \dots$  linear H. anf  $x, x' = \dots$

$$x' = \frac{x x + h}{v x + p}$$

$$y p x_1 = \lambda x_1 + \mu x_2$$

$$y p x_2 = v x_1 + p x_2 \quad | \dots \text{proportional factors}$$

$$x_1' = \lambda x_1 + p x_2$$

$$x_2' = v x_1 + p x_2$$

$$\Delta = \lambda p - p v \neq 0$$

$\Delta \neq 0$  determinant invertible  $x, x' = \dots$

$x, x' = \dots$  homog. linear eq.  $x, x' = \dots$

$$a_0 x_1 + a_1 x_2 = 0$$

$$\frac{x_1}{x_2} = \frac{a_1}{a_0}$$

is a point  $(x_1, x_2)$

quadr. homog. eq. two pts in line  $\Rightarrow$  2 pts  
 - is on the def. homog. algebraic eq.

$$f = a_0 x_1^n + a_1 x_1^{n-1} x_2 + \dots + a_{n-1} x_1 x_2^{n-1} + a_n x_2^n = 0$$

is a pt. syst. on a line  $\Rightarrow$  2 pts  $\Rightarrow$  binary form

Def. I. A binary form, coeff. in  $K$ , is a homogeneous polynomial of degree  $n$  in two variables  $x_1, x_2$ .  
 invariant  $\Rightarrow$  (if  $f$  is a binary form of degree  $n$ , then  $I(a_0, a_1, \dots, a_n) = k I(a_0', a_1', \dots, a_n')$ )

$I(a_0, a_1, a_2, \dots, a_n)$  is a rational function of the coefficients  $(a_1, a_2, \dots, a_n)$ .  
 $I$  is the invariant.

$I(a_0', a_1', a_2', \dots, a_n') = k I(a_0, a_1, a_2, \dots, a_n)$   
 $(k = \dots)$   
 invariant  $\Rightarrow$  index of invariant

Binary form invariant  $\Rightarrow$  0. Every eq. has a projective property.  
 Ex. 1. binary quadratic form  $f = a_0 x_1^2 + 2a_1 x_1 x_2 + a_2 x_2^2$   
 its discriminant is  $4(a_1^2 - a_0 a_2)$

$$D = a_0 a_2 - a_1^2$$

is a rational invariant of  $f$

$$D' = a_0' a_2' - a_1'^2 = \Delta^2 D$$

$\Delta D$  is invariant of index 2  $\Rightarrow$  2 pts

$D = 0 \Rightarrow$  quad. form is a pair of lines  $\Rightarrow$  2 pts  
 coincide  $\Rightarrow$  1 pt  $\Rightarrow$  proj.  $\Rightarrow$  3 pts  $\Rightarrow$  2 pts

II. Let  $K(a_0', a_1', \dots, a_n'; x_1, x_2) = \dots$   
 $\Delta^2 K(a_0, a_1, \dots, a_n; x_1, x_2)$

coeff.  $\Rightarrow$  rational invariant of  $f$  is a binary form of degree  $2n$ .  
 $\Delta^2 K$  is a covariant of index  $2n$ .

$\Rightarrow$  invariant  $\Rightarrow$  0. Every eq. has a projective property  $\Rightarrow$  invariant  $\Rightarrow$

Ex. 2 
$$h = \begin{vmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_2^2} \end{vmatrix}$$
 is  $f$ 's Hessian  $\Rightarrow$  0 Hessian  $\Rightarrow$

$$h' = \Delta^2 h$$

Hessian index 2, covariant  $\Rightarrow$   
 $h = 4(a_1^2 - a_0 a_2)$  for binary quadratic form  $f$   
 cubic form  $f = a_0 x_1^3 + 3a_1 x_1^2 x_2 + 3a_2 x_1 x_2^2 + a_3 x_2^3$

$$1.14. \quad h = [(a_0 a_2 - a_1^2)x_1^2 + (2a_0 a_1 - a_1^2)x_1 x_2 + (a_1 a_2 - a_2^2)x_2^2]$$

1.15.  $f_1, f_2$  linear forms, syst. as simultaneous quadratic  
 simultaneous quad.  $2 \times 2$   $2 \times 2$

$$\text{Ex. 3.} \quad \begin{aligned} f_1 &= a_0 x_1^2 + 2a_1 x_1 x_2 + a_2 x_2^2 \\ f_2 &= b_0 x_1^2 + 2b_1 x_1 x_2 + b_2 x_2^2 \\ \Theta &= a_0 b_0 + a_1 b_1 + a_2 b_2 \end{aligned}$$

is harmonic:  $\Theta = 0$

$$\Theta' = 2\Theta$$

if  $\Theta = 0$ ,  $f_1, f_2$  simult. quad. = 5 indep.  $2 \times 2$

$\Theta = 0$   $f_1 = 0, f_2 = 0$ ,  $\frac{1}{2}\Theta = 0$  pt. is harmonic  
 inally: separate  $\rightarrow$   $\frac{1}{2}\Theta = 0$   $\rightarrow$  proj. prop.

$$\text{Ex. 4.} \quad J = \begin{vmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{vmatrix} \quad \text{det. } f_1, f_2 \text{ Jacobian}$$

$$J' = 2J$$

Jacobian is indep. 1, covariant  $\rightarrow$

$$f_1 = a_0 x_1^2 + 2a_1 x_1 x_2 + a_2 x_2^2$$

$$f_2 = b_0 x_1^2 + 2b_1 x_1 x_2 + b_2 x_2^2$$

$$J = 2[(a_0 b_1 - a_1 b_0)x_1 + (a_1 b_2 - a_2 b_1)x_2]$$

$$f_1 \quad f_2 \quad f_1'' \quad J$$

$\Theta =$  harmonic  $\rightarrow$   $\frac{1}{2}\Theta =$  Jacobian  $f_1$  harmonic

$\rightarrow$  proj. prop.  $\rightarrow$

$$\text{Ex. 5.} \quad \begin{aligned} f_1 &= a_0 x_1^2 + 2a_1 x_1 x_2 + a_2 x_2^2 \\ f_2 &= b_0 x_1^2 + 2b_1 x_1 x_2 + b_2 x_2^2 \end{aligned}$$

$$J = (a_0 b_1 - a_1 b_0)x_1 + (a_1 b_2 - a_2 b_1)x_2$$

$$\Theta(f_1, J) = 0 \quad \Theta \text{ is identically 0}$$

$$\Theta(f_2, J) = 0 \quad \text{identically}$$

$$J' = 2J$$

$J', J'' = 2J, 2J'$  harmonic = separate quad.  $2 \times 2$

$\rightarrow$  involut. double pt.  $\rightarrow$   $\frac{1}{2}\Theta = 0$

$$J', J'' \text{ in } f_1 = 0, f_2 = 0 \text{ point}$$

invol. double pt.  $\rightarrow$   $\frac{1}{2}\Theta = 0$

$$J = 0 \quad \text{covariant}$$

Ex. 3.  $\Theta = 0$   $\rightarrow$  invol.  $\rightarrow$

$f_1, f_2$  with deg.  $k$   $\rightarrow$   $f_1 + k f_2$  with deg.  $k$   $\rightarrow$   $f_1 + k f_2$

$$I(a_0, a_1, \dots, a_n) \text{ is } f_1 \text{ invariant}$$

$$I(a_0 + k b_0, a_1 + k b_1, \dots, a_n + k b_n)$$

$$= \Delta^n I(a_0, k b_0, a_1 + k b_1, \dots, a_n + k b_n)$$



-th = f(x, y, z) - nth binary f. 1. 2. 3. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

$$f(x, y, z) = f(z, z, z) + \frac{n}{1!} f''(y, z, z) + \frac{n(n-1)}{2!} f'''(y, z, z) + \dots + f''(z, z, z) = 0$$

1st polar  $f'(x, y, z) = 0$

$$(y \frac{\partial}{\partial x} + z \frac{\partial}{\partial y}) f(x, y, z) = 0$$

2nd polar  $f''(x, y, z) = 0$

1st polar  $f'(x, y, z) = 0$  n roots sum 0

$$\frac{y}{z} + \frac{y}{z} + \dots + \frac{y}{z} = 0 \quad 3 \text{ p.s.m.}$$

$$\frac{y}{z} = \frac{1}{z} + \frac{1}{z} + \dots + \frac{1}{z}$$

center  $f(x, y, z) = 0$  harmonic

ex. 7. Cubic form  $f = 1. 2. 3.$

$$f = a_0 x^3 + \dots$$

2. second polar  $f'' = 0$

$$(a_0 y + a_1 y^2) z^2 + 2(a_1 y + a_2 y^2) z + (a_2 y + a_3 y^2) = 0$$

double pt  $f'' = 0$

$$(a_0 a_2 - a_1^2) y^2 + (a_0 a_3 - a_1 a_2) y + (a_1 a_3 - a_2^2) = 0$$

4th cubic f. Hessia = 87 + 30

5th cubic f. Hessia = 0. 1. equal - pt. eqpt. y

6th cubic f. Hessia = 0. 1. equal - pt. eqpt. y

7th cubic f. Hessia = 0. 1. equal - pt. eqpt. y

V.  $I_1 = \Delta^{\lambda_1} I_1, I_2 = \Delta^{\lambda_2} I_2, \dots, I_n = \Delta^{\lambda_n} I_n$

$$I_1' = \Delta^{\lambda_1} I_1 + \dots$$

$$\frac{I_1'}{I_1} = \frac{\Delta^{\lambda_1} I_1}{\Delta^{\lambda_1} I_1} = \frac{I_1'}{I_1}$$

absolute invariant  $\rightarrow$   $\frac{I_1'}{I_1}$

ex. 8. four pts eqpt. to anharmonic ratio

absolute inv  $\rightarrow$

Theory of invariants. Invariant, covariant, mixed covariant.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

algebra  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$  Binary form  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

1st rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

2nd rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

3rd rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

4th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

5th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

6th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

7th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

8th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

9th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

10th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

11th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

12th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

13th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

14th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

15th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

16th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

17th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

18th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

19th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

20th rank, elem. f.  $\rightarrow$   $\frac{I_1'}{I_1}, \frac{I_2'}{I_2}, \dots$

















(x, y) pt. is invariant pt. is

$$x = \frac{a_1 x + b_1 y + c_1}{a_2 x + b_2 y + c_2} \quad y = \frac{a_1 x + b_1 y + c_1}{a_2 x + b_2 y + c_2}$$

3. to i. p. 1. E 4.

$$\begin{cases} p x = a_1 x + b_1 y + c_1 \\ p y = a_2 x + b_2 y + c_2 \\ p = a_1 x + b_1 y + c_1 \end{cases} \quad \begin{cases} (a_1 - p)x + b_1 y + c_1 = 0 \\ a_2 x + (b_2 - p)y + c_2 = 0 \\ a_2 x + b_2 y + (c_2 - p) = 0 \end{cases}$$

the linear eq. 0, 0, 0.  $\neq 0$   $\rightarrow$   $\dots$

$$\begin{vmatrix} a_1 - p & b_1 & c_1 \\ a_2 & b_2 - p & c_2 \\ a_2 & b_2 & c_2 - p \end{vmatrix} = 0$$

the p. is cubic eq.  $\rightarrow$  3 roots.

1, 2, 3. real  $\rightarrow$  the p. values eq.  $\rightarrow$   $\dots$

xy  $\rightarrow$  the p. is  $\dots$

Theorem general collineation is  $\dots$  invariant line  $\rightarrow$

pt.  $\rightarrow$   $\dots$  real  $\rightarrow$

invariant pts.  $\rightarrow$   $\dots$  invariant line  $\rightarrow$

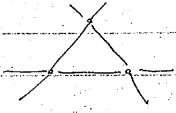
Remark  $\rightarrow$   $\dots$  invariant line  $\rightarrow$

2.  $\rightarrow$  coincident  $\rightarrow$   $\dots$  cubic

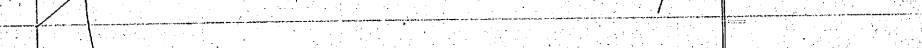
eq.  $\rightarrow$  quadratic or linear eq.  $\rightarrow$  reduce  $\rightarrow$

$\rightarrow$   $\dots$   $\rightarrow$   $\dots$

type I.



II.  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$



IV.  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$



2.  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

infinite  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

classifies as (Lill, Vorlesungen in Continuummechanik

Krupp (1893),  $\rightarrow$  Meyer, Chicago Congress

Papers 1898, Newcom, Amer. J. M. 24 (1902)

Binomial form  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

gen.  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

invariant plane  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

gen.  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

cubic curve, proj. gen.  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

cubic quartic  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

Salmon  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

invariant. Chasles-Dixon  $\rightarrow$   $\dots$   $\rightarrow$   $\dots$

Brodyer, Leçons sur la théorie des formes, t. 1

$\rightarrow$   $\dots$

6.6. Infiniteesimal projective transformations (proj. tr.)  
 collimat.  $i = 1, 2, \dots$

die  $i$  to  $2n$  proj. g. s. 2. p. d. error in

space plane =  $x, y, z$

$$x_i = \frac{a_i x + b_i y + c_i}{a_3 x + b_3 y + c_3}, \quad y_i = \frac{a_i x + b_i y + c_i}{a_3 x + b_3 y + c_3}$$

2. identical  $u, v$

$$a_1 = 1, \quad b_1 = 0, \quad c_1 = 0$$

$$a_2 = 0, \quad b_2 = 1, \quad c_2 = 0$$

$$a_3 = 0, \quad b_3 = 0, \quad c_3 = 1$$

set: coeff. s. infinit.  $\rightarrow$   $\delta x$

$$a_1 = 1 + \delta_1 dt, \quad b_1 = \beta_1 dt, \quad c_1 = \gamma_1 dt$$

$$a_2 = \alpha_2 dt, \quad b_2 = 1 + \rho_2 dt, \quad c_2 = \gamma_2 dt$$

$$a_3 = \alpha_3 dt, \quad b_3 = \rho_3 dt, \quad c_3 = 1 + \gamma_3 dt$$

$\alpha, \beta, \gamma$  arbitrary const.  $\rightarrow$   $dt$  infinit

quantity  $\rightarrow$

$$x_i = \frac{x + (\alpha_1 x + \beta_1 y + \gamma_1) dt}{1 + (\alpha_3 x + \beta_3 y + \gamma_3) dt}, \quad y_i = \frac{y + (\alpha_2 x + \beta_2 y + \gamma_2) dt}{1 + (\alpha_3 x + \beta_3 y + \gamma_3) dt}$$

$\rightarrow$   $dt$ , from series expansion

$$x_i = x + [\gamma_1 + (\alpha_1 - \gamma_3)x + \beta_1 y - \alpha_3 x^2 - \beta_3 xy] dt + \dots$$

$$y_i = y + [\gamma_2 + \alpha_2 x + (\beta_2 - \gamma_3)y - \alpha_3 xy - \beta_3 y^2] dt + \dots$$

$(dt) \rightarrow \delta x, \delta y$

$$\delta x = x_i - x = (a + cx + dy + hx^2 + kxy) dt,$$

$$\delta y = y_i - y = (b + ex + gy + hxy + ky^2) dt$$

$u = f(x, y)$   $\rightarrow$  continuous, differentiability  $\delta x, \delta y$   
 t. permutable  $\rightarrow$

$$\delta f = f(x_i, y_i) - f(x, y) = f(x + \delta x, y + \delta y) - f(x, y) \\ = f(x, y) + \frac{\partial f}{\partial x} \delta x + \frac{\partial f}{\partial y} \delta y - f(x, y) \\ = \frac{\partial f}{\partial x} \delta x + \frac{\partial f}{\partial y} \delta y$$

$\delta x, \delta y$  in  $\rightarrow$

$$\delta f = \left\{ (a + cx + dy + \dots) \frac{\partial f}{\partial x} + (b + ex + \dots) \frac{\partial f}{\partial y} \right\} dt$$

$$Uf = \left\{ (a + cx + dy + hx^2 + kxy) \frac{\partial f}{\partial x} + (b + ex + gy + hxy + ky^2) \frac{\partial f}{\partial y} \right\} dt$$

$Uf$  infinites. proj. tr. symbol  $\rightarrow$

$$Ux = a + cx + dy + hx^2 + kxy$$

$$Uy = b + ex + gy + hxy + ky^2$$

$Uf$  constant a b c d e g h k  $\rightarrow$  general  $\rightarrow$  inf. proj. tr. s. special inf. proj. tr.  $\rightarrow$  p, q:  $xp, yp, xq, yq; x^2p + xyq, xy^2p + y^2q$  i. combin.  $\rightarrow$   $\rightarrow$

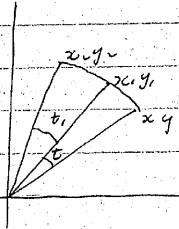
ex. 1.  $Uf = x \frac{\partial f}{\partial x} + y \frac{\partial f}{\partial y}$   $\rightarrow$   $\rightarrow$  collimat.  $\rightarrow$

$$\delta x = x_i - x = (a + cx + \dots) dt = \sigma x dt$$

$$\delta x = x dt, \quad \delta y = y dt$$



$$\begin{cases} x_1 = x \cos(t+t_1) - y \sin(t+t_1) \\ y_1 = x \sin(t+t_1) + y \cos(t+t_1) \end{cases}$$



Ex. 3.  $\nabla f = xp + yq$  inf. similar transformation

$$\begin{aligned} dx &= x dt, & dy &= y dt \\ \frac{dx}{x} &= \frac{dy}{y} = dt & x_1 &= x, & y_1 &= y \text{ for } t=0 \end{aligned}$$

$$x_1 = x e^t, \quad y_1 = y e^t$$

$$x_1 = x e^{t_1}, \quad y_1 = y e^{t_1}$$

$$x_1 = x e, \quad y_1 = y e$$

Theorem: Inf. group  $\mathbb{R}$  is a one parameter group. Proj. transformation  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ . finite group  $\mathbb{Z}$  is a discrete inf. group  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ .  $\mathbb{Z}$  is a group of finite proj.  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ .

$$\frac{dx}{a+bx} = \frac{dy}{b+cx} = dt, \quad x_1 = x, \quad y_1 = y \text{ for } t=0$$

to solve:  $x_1 = \frac{a_1 x + b_1 + c_1}{a_2 x + b_2 + c_2}, \quad y_1 = \frac{a_2 x + b_2 y + c_2}{c_2 x + b_2 y + c_2}$

a, b, c arbitrary fct. of t  $\rightarrow \mathbb{R}^2 \rightarrow \mathbb{R}^2$   $\rightarrow \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a group. See Ex. 4-49.

Lin. Diff. Gleich. Kap. 16. § 3.  $x' = 3x, y' = 3y, z' = 3z$

62. Invariant points, invariant curves  
path curves.

inf.  $\nabla f = \xi p + \eta q$  in  $dx = \xi dt, \quad dy = \eta dt$

$\xi = 0, \eta = 0$  is a point  $\rightarrow$  invariant pt.  $\rightarrow$   $\frac{dx}{\xi} = \frac{dy}{\eta} = dt$

invariant pt.  $\rightarrow$   $\frac{dx}{\xi} = \frac{dy}{\eta}$   $\rightarrow$   $\frac{dx}{3} = \frac{dy}{y}$   $\rightarrow$   $\ln x = \ln y + C$   $\rightarrow$   $x = y e^C$

path curve (Balken)  $\rightarrow$   $\frac{dy}{dx} = \frac{\eta}{\xi}$

to solve:  $\frac{dy}{dx} = \frac{\eta}{\xi}$  curves

path curve  $\rightarrow$   $\frac{dy}{dx} = \frac{\eta}{\xi}$  invariant curve  $\rightarrow$   $\frac{dy}{dx} = \frac{\eta}{\xi}$   $\rightarrow$   $\frac{dy}{y} = \frac{dx}{x}$   $\rightarrow$   $\ln y = \ln x + C$   $\rightarrow$   $y = x e^C$

to solve:  $\frac{dy}{dx} = \frac{\eta}{\xi}$   $\rightarrow$   $\frac{dy}{y} = \frac{dx}{x}$   $\rightarrow$   $\ln y = \ln x + C$   $\rightarrow$   $y = x e^C$

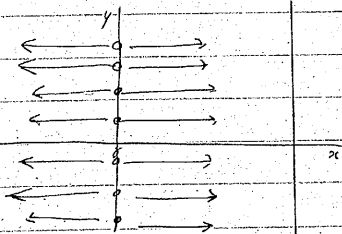
Ex. 1.  $\nabla f = xp$

$$dx = x dt, \quad dy = 0 dt$$

$$\frac{dx}{x} = \frac{dy}{y} = dt \quad x_1 = x, \quad y_1 = y \text{ for } t=0$$

$$x_1 = x e^t \quad y_1 = y$$

y axis: inv. curve +  
y = const. o. path curve +



Ex. 2  $\nabla f = -y p + x q$  rotati

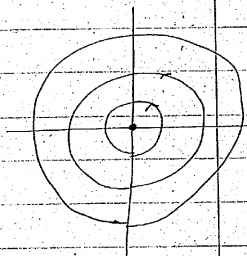
orig. in var. pt.  
concentric circ. path curve

$$-y = 0, x = 0 \quad \text{orig.}$$

$$\frac{dx}{-y} = \frac{dy}{x}$$

$$x dx + y dy = 0$$

$$\therefore x^2 + y^2 = \text{const.}$$



rot. Li. theory -> co. 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100

rot. wuf. li. path curve

$$\frac{dx}{a+cx+dy+hx+ky} = \frac{dy}{b+ex+gy+lx+my}$$

Li. diff. eq. = Jacobi's diff. eq.

Te. an. sol. Serret-Schiffus. diff. und. P. III

2. Contact. Analyse II. p. 321 (Darboux's method)

3. geom. considerati. in 3D

Te. 3.1. coord. axis:  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  in v. line

x, y axis, line at co. = ...

$$dx = (a+cx+dy+hx+ky) dt$$

$$dy = (b+ex+gy+lx+my) dt$$

$$x=0, y=0 \quad \text{var. pt.}$$

$$a=0, y=0$$

$$x=0, y=0 \quad \text{var. pt.}$$

$$x = \text{const.} \quad \text{so } dx = 0 \quad \text{parallel to y-axis}$$

$$\therefore dx \cdot y = \text{independent}$$

$$\partial d = 0, k = 0$$

$$\text{rot. } \nabla f = -y p + x q \quad e=0, h=0$$

$$\int dx = cx dt$$

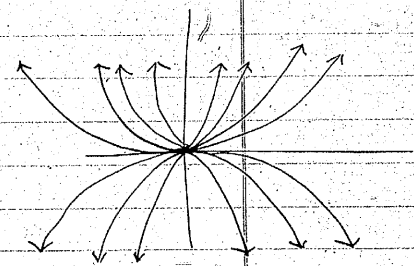
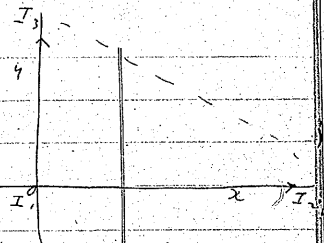
$$\int dy = gy dt$$

$$\nabla f = cx \frac{df}{dx} + gy \frac{df}{dy}$$

$$\frac{dx}{cx} = \frac{dy}{gy}$$

$$\frac{1}{c} \log x = \frac{1}{g} \log y + \log k_1$$

$$x^c y^{-g} = k_1$$



3.3 - 12.13 = ... homog. coord.

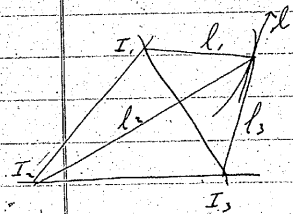
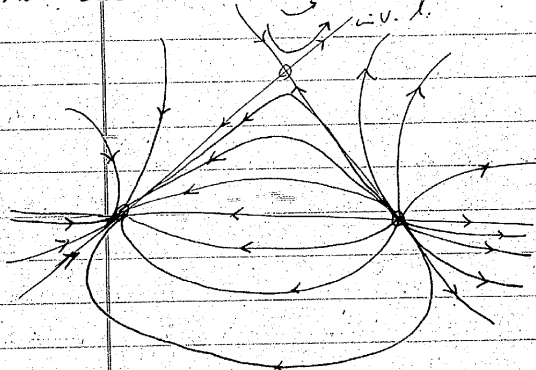
$$\frac{x_1}{x_2} = x, \quad \frac{y_1}{y_2} = y$$

$$x_1^c x_2^g x_3^{-c+g} = k,$$

$$x_1^{\lambda_1} x_2^{\lambda_2} x_3^{\lambda_3} = k, \quad \lambda_1 + \lambda_2 + \lambda_3 = 0.$$

$$-k = uv \text{ line } \dots x_1 = 0, x_2 = 0, x_3 = 0, \dots$$

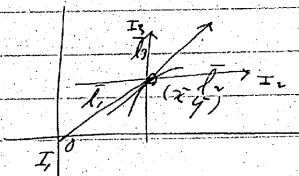
$$\text{path curve } x_1^{\lambda_1} x_2^{\lambda_2} x_3^{\lambda_3} = k, \dots$$



$l_i$  tangent

$$R_4(l_1, l_2, l_3, l_4)$$

$g, h$ : special case =  $3, 2, 1, 4$



$$l : y - \bar{y} = \frac{dy}{dx} (x - \bar{x}) = \frac{g\bar{y}}{c\bar{x}} (x - \bar{x})$$

$$l_1 : y - \bar{y} = \frac{y}{x} (x - \bar{x})$$

$$l_2 : y - \bar{y} = 0 \cdot (x - \bar{x})$$

$$l_3 : y - \bar{y} = \infty \cdot (x - \bar{x})$$

$$R_4 = \frac{c\bar{y} - \frac{y}{x}}{c\bar{x} - 0} : \frac{\frac{g\bar{y}}{c\bar{x}} - \frac{y}{x}}{\frac{g\bar{y}}{c\bar{x}} - 0} = \frac{g}{g - c}$$

$ca = \text{path } c, \dots, (2, 2, \text{pt } M, \text{ tang. of } l, \dots)$

$l, M_1, M_2, M_3$ : double points  $l_1 = l_2$

$uv = -h + \dots$ , Klein, Lie: 1870: de curv.

$W$  curve:  $W$ -curve:  $W$ -surface:  $W$ -stand:  $W$ :

let rank, etc. form 4 elements:  $W$ -surface

$W$ -surface =  $W$ -surface =  $W$ -surface:  $W$ -surface:  $W$ -surface

and  $W$ -surface & Weingarten's surface:  $W$ -surface

$W$ -surface: Klein, Lie: 1870:  $W$ -surface:  $W$ -surface

$W$ -surface: Jordan:  $W$ -surface:  $W$ -surface:  $W$ -surface

$W$ -surface:  $W$ -surface:  $W$ -surface:  $W$ -surface

$W$ -surface:  $W$ -surface:  $W$ -surface:  $W$ -surface

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$W$ -surface:  $W$ -surface:  $W$ -surface:  $W$ -surface

$W$ -surface:  $W$ -surface:  $W$ -surface:  $W$ -surface

$$W \text{ eq } x_1^{\lambda_1} x_2^{\lambda_2} x_3^{\lambda_3} = k \quad (x_1 + x_2 + x_3 = 0)$$

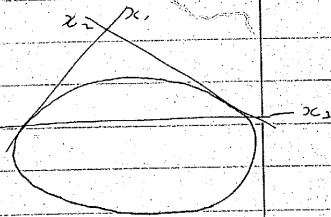
particular curve



1.  $\lambda_1 = 1, \lambda_2 = 1, \lambda_3 = -2$

$x_1, x_2 = k x_3$

we: conic +



11.  $\frac{x_1}{x_3} = x + iy$

$\frac{x_2}{x_3} = x - iy$

$x_1, x_2$  rectangular coords. +

$x_1 = 0, x_2 = 0$  minimal line

$x_3 = 0$  line at  $\infty$

0.  $\phi, \bar{\phi}$  (circular pt at  $\infty$ ) +

invariant  $\frac{x_1 - \lambda_1 x_3}{x_2 - \lambda_2 x_3}$  conic +

$\frac{x_1 - \lambda_1 x_3}{x_2 - \lambda_2 x_3} = k$  i.e.  $\lambda$  arbitrary const

we W-conic  $\frac{x_1 + iy}{x_2 - iy} = k$

$\frac{(x_1 + iy)(x_2 + iy)}{(x_2 - iy)(x_1 - iy)} = k$

i.e. polar coord. =  $e^{i\theta}$   $x = r \cos \theta, y = r \sin \theta$

$x + iy = r(\cos \theta + i \sin \theta) = r e^{i\theta}$

$x - iy = r(\cos \theta - i \sin \theta) = r e^{-i\theta}$

$\frac{x + iy}{x - iy} = e^{2i\theta}$

$r e^{-\lambda \theta} = k$

$r = k e^{\lambda \theta}$  logarithmic spiral

we: W-conic part case conic Klein, p. 2 +

W-conic, i.e. + 2.3. in. Geog. p. III 3, Heft. 2/3

Loria, Spezielle Kurven II, p. 178 = 2.3



63. Extended transformations differential invariants

$\xi(x, y), \eta(x, y)$   $x, y$  analytic funct. +

$dx = \xi dt, dy = \eta dt$

$Uf = \xi p + \eta q$

we:  $Uf = 0$  = infinitesimal point transformation

i.e.  $x = \xi, y = \eta$  vary

we: 2.3. in. conic

$dy' = d \frac{dy}{dx} = \frac{d^2 y}{dx^2} dx - dy \frac{d^2 x}{dx^2}$

$= \frac{d^2 y}{dx^2} dx - dy \frac{d^2 x}{dx^2} = \frac{d^2 y}{dx^2} - y' \frac{d^2 x}{dx^2}$

$= \left( \frac{d\eta}{dx} - y' \frac{d\xi}{dx} \right) dt$

$y' = \frac{dy}{dx}$

$dy' = [\eta_x + \eta_y y' - y'(\xi_x + \xi_y y')] dt$

$dy' = [\eta_x + (\eta_y - \xi_y) y' - \xi_x] dt$

Def.  $dx = \xi dt, dy = \eta dt, dy' = \dots$

1st extended transform +  $dy'' = \dots$

ext. h. i. 43

$$dy'' = \frac{d dy'}{dx} - y'' \frac{dx}{dx}$$

$$dy'' = [\eta_{xx} + (2\eta_{xy} - \xi_{xx})y' + (\eta_{yy} - 2\xi_{xy})y'^2 - \xi_{yy}y'^3 + (\eta_y - 2\xi_x - 3\xi_y y')y''] dx$$

$$dy'' =$$

Theorem  $\{ \eta, \xi \} = 0 \Leftrightarrow$  var.  $\xi, \eta = 0 \Leftrightarrow \xi = 0 = \eta$

us. inf. h. inf. proj. h.  $\Leftrightarrow$

Proof  $y'' = 0$  i.v.  $\Leftrightarrow$   $y = ax + b$   $\Leftrightarrow$   $y'' = 0$

$y'' = 0$  const.  $\Leftrightarrow$   $dy'' = 0$   $\Leftrightarrow$   $\xi = 0 = \eta$

$$dy'' = [ \quad ] dx$$

coeff.  $\equiv 0$

$$\begin{cases} \eta_{xx} = 0 & \eta_{yy} - 2\xi_{xy} = 0 \\ \xi_{yy} = 0 & \xi_{xx} - 2\eta_{xy} = 0 \end{cases}$$

$$\begin{cases} \xi = Xy + X_0 & X \text{ x.c. funct.} \\ \eta = Yx + Y_0 \end{cases}$$

$$\begin{cases} \eta_y = 2\xi_x = X_1 \\ \xi_{xx} - 2\eta_{xy} = Y_1 \end{cases}$$

ii. soluc.

$$\begin{cases} 3\xi_x = -2X_1 - Y_1 \\ 3\eta_y = -2Y_1 - X_1 \end{cases}$$

$$\begin{cases} 3X'y + 3X_0 = -2X_1 - Y_1 \\ 3Y'x + 3Y_0 = -2Y_1 - X_1 \end{cases}$$

ii.  $X_1, Y_1$  linear f.  $Y_1 = -3cy - 3d$   $\Leftrightarrow$   $X_1 = -3ax - 3b$

$$X = cx + r, Y = ay + d$$

$$X_0 = 2ax + 2b + d$$

$$Y_0 = 2cy + 2d + b$$

$$X_0 = ax^2 + (2b+d)x + \beta$$

$$Y_0 = cy^2 + (2d+b)y + \delta$$

$$\xi = Xy + X_0, \eta = Yx + Y_0 = x$$

$$\xi = (cx+r)y + ax^2 + (2b+d)x + \beta$$

$$\eta = (ay+d)x + cy^2 + (2d+b)y + \delta$$

$$df = (a_1 + c_1x + d_1y + h_1x^2 + k_1xy) dx + (b_1 + e_1x + g_1y + h_1xy + k_1y^2) dy$$

ii. inf. proj. h.  $\Leftrightarrow$

Remarks  $\xi = y'' = 0 \Leftrightarrow$  inf. proj. h.  $\Leftrightarrow y'' = 0$   $\Leftrightarrow$  differential (proj.) in variant

Remark Conic collineat.  $\Leftrightarrow$  conic  $\Leftrightarrow$

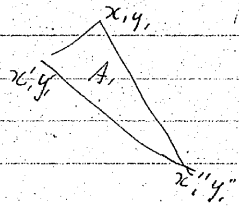
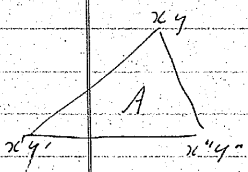


8. parabola eq  $y = mx + n + \sqrt{2Bx+c} + y$   
 $y'' = \frac{-B}{(2Bx+c)^{3/2}} \quad (y'')^{-2/3} = (-B)^{-2/3} (2Bx+c)$

$\frac{d}{dx} [(y'')^{-2/3}] = 0 \quad \text{or} \quad 5y''' = 3y'' y' = 0$

aff. h.  $\rightarrow$   $u, v, z \rightarrow \mathbb{E} = \mathbb{R}^3$ , parabola  $\rightarrow \mathbb{A}^1$   
 parabola  $\rightarrow \mathbb{A}^1$  in  $\mathbb{E}$  aff. h.  $\rightarrow$   $\mathbb{R}^3$  or  $\mathbb{E}$   
 $u, v, z \rightarrow \mathbb{E}$  aff. h.  $\rightarrow \mathbb{E}$   
 Theorem 4 closed curve area aff. h.  $\rightarrow$   
 relative invariant  $\rightarrow$

$\Delta = \rightarrow + \rightarrow + \rightarrow \dots \rightarrow + \rightarrow \quad A_0, \text{ area } A, \dots$



$A_1 = \Delta A$

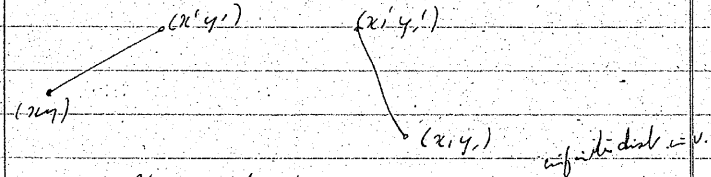
$\Delta = \begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}$

$\begin{cases} x_1 = a_1 x + b_1 y + c_1 \\ y_1 = a_2 x + b_2 y + c_2 \end{cases} \quad \begin{cases} x'_1 = a_1 x' + b_1 y' + c_1 \\ y'_1 = a_2 x' + b_2 y' + c_2 \end{cases}$   
 $\begin{cases} x''_1 = a_1 x'' + b_1 y'' + c_1 \\ y''_1 = a_2 x'' + b_2 y'' + c_2 \end{cases}$

$$\begin{vmatrix} 1 & 1 & 1 \\ x_1 & x'_1 & x''_1 \\ y_1 & y'_1 & y''_1 \end{vmatrix} = \begin{vmatrix} 0 & 0 & 1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} \begin{vmatrix} x & y & 1 \\ x' & y' & 1 \\ x'' & y'' & 1 \end{vmatrix}$$

$2A_1 = \Delta \cdot 2A$

6.5 Group of motion (rigid body)  
 $\rightarrow$  pt  $(x, y)$  to  $(x', y')$  + distance + absolute  
 invar.  $\rightarrow$   $\rightarrow$   $\rightarrow$  coll.  $\rightarrow$   $\rightarrow$



2. coll.  $\rightarrow$  pt at  $o_1$  pt at  $o_2 = \rightarrow$  in affine  
 $\mathbb{E} \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow$

$\begin{cases} x_1 = a_1 x + b_1 y + c_1 \\ y_1 = a_2 x + b_2 y + c_2 \end{cases}$   
 $\begin{cases} x'_1 = a_1 x' + b_1 y'_1 + c_1 \\ y'_1 = a_2 x' + b_2 y'_1 + c_2 \end{cases}$

dist. absolute value  $\rightarrow$   
 $(x_1 - x'_1)^2 + (y_1 - y'_1)^2 = [a_1(x - x') + b_1(y - y')]^2 + [a_2(x - x') + b_2(y - y')]^2$   
 $= (x - x')^2 + (y - y')^2 \rightarrow \rightarrow$

$a_1^2 + a_2^2 = 1$      $b_1^2 + b_2^2 = 1$      $a_1 b_1 + a_2 b_2 = 0$   
 nec. necessary + suff. and  $\Rightarrow$  orthogonal transform  
 $\begin{cases} a_1 = \cos \alpha & b_1 = \cos \beta \\ a_2 = \sin \alpha & b_2 = \sin \beta \end{cases}$      $\vec{E} \Rightarrow \vec{E} + \vec{v}$   
 $\cos(\alpha - \beta) = 0$      $\beta = \alpha + (n+1)\frac{\pi}{2}$   
 $n = 0, 1, 2, \dots$

$\begin{cases} b_1 = (-1)^n \cos \alpha \\ b_2 = (-1)^{n+1} \sin \alpha \end{cases}$

Case  $n=0$

$\begin{cases} a_1 = \cos \alpha & a_2 = \sin \alpha & b_1 = -\sin \alpha & b_2 = \cos \alpha \end{cases}$

$\begin{cases} x_1 = x \cos \alpha - y \sin \alpha + a \\ y_1 = x \sin \alpha + y \cos \alpha + b \end{cases}$

congruence + translation

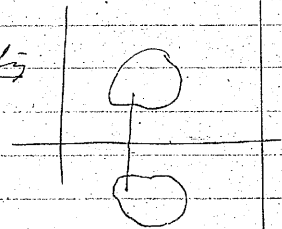
and axis displacement + rotation

$\begin{cases} x_1 = x \cos \alpha + y \sin \alpha + a \\ y_1 = x \sin \alpha - y \cos \alpha + b \end{cases}$

or  $y \rightarrow -y$  = reflection

x axis:  $\Rightarrow$  reflect, symmetry

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1. 1. 1. 3.  $\vec{E} \Rightarrow \vec{E} + \vec{v}$     group  $\Rightarrow \vec{E} + \vec{v}$

comb.  $\Rightarrow$   $\vec{E} \Rightarrow \vec{E} + \vec{v}$     dist    const

def. continuous group  $\Rightarrow \vec{E} + \vec{v}$

Def. Congruence  $\Rightarrow$  1. case  $\Rightarrow$  const. group  $\Rightarrow$  the  
 2. 1. 1. 1. 3. 1. 3. 1. 3. group: mixed (gemischt) group  
 3. 1. 1. 1. 3. 1. 3. 1. 3.

group of mot. identical  $\Rightarrow a=0, b=0, \alpha=0$

$\alpha = 2n\pi + \lambda dt$      $a = \mu dt$      $b = \nu dt$     Variations  
 $\begin{aligned} dx &= x - x = x \cos(2n\pi + \lambda dt) - y \sin(2n\pi + \lambda dt) \\ &\quad + \mu dt - x \\ &= x[1 - \frac{\lambda^2 dt^2}{2!} \dots] - y[\lambda dt] + \mu dt \end{aligned}$

end diff.  $\Rightarrow \vec{E} + \vec{v}$

$dx = (-\lambda y + \mu) dt$

$dy = (\lambda x + \nu) dt$

infin mot. symbol:

$\begin{aligned} Df &= (-\lambda y + \mu)p + (\lambda x + \nu)q \\ &= \lambda(xq - yp) + \mu p + \nu q \end{aligned}$

if inf mot.  $xq - yp$ ,  $p, q$  : composition  $\Rightarrow$  1. 1. 1. 3.

$xq - yp$  : origin, 1. 1. 1. 3. rotation  $\Rightarrow$  (1. 1. 1. 3. 2.)

$p, q$  : translation  $\Rightarrow$

$\mu p + \nu q$  : first form  $\Rightarrow$   $x_1 = x + \mu t$

$y_1 = y + \nu t$

$\frac{dx_1}{\mu} = \frac{dy_1}{\nu} = dt$

$\begin{cases} x_1 = x \\ y_1 = y \end{cases}$  first  $t=0 = \vec{E}$







$$dx = (x + \beta x + \gamma x^2) dt$$

$$U.f = (x + \beta x + \gamma x^2) \frac{df}{dx}$$

3 term cont group

lim + any one pt, any two pts, any 3 pts

proper sense, i.e. + i.e. 2 pts, 3 pts, 4 pts

1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100

4 v

$$x, x', x'', x''', x^{(4)}, \dots \in \mathbb{R}$$

$$\Omega(x, x', x'', x''') = \Omega(x, x', x'', x''')$$

4 const:  $\alpha, \beta, \gamma, \delta$

$$\frac{\partial \Omega}{\partial x} dx + \frac{\partial \Omega}{\partial x'} dx' + \frac{\partial \Omega}{\partial x''} dx'' + \frac{\partial \Omega}{\partial x'''} dx''' = 0$$

$$(\alpha + \beta x + \gamma x^2) \frac{\partial \Omega}{\partial x} + (\alpha + \beta x + \gamma x^2) \frac{\partial \Omega}{\partial x'} + (\dots) \frac{\partial \Omega}{\partial x''} + (\dots) \frac{\partial \Omega}{\partial x'''} = 0$$

$$\alpha \left( \frac{\partial \Omega}{\partial x} + \frac{\partial \Omega}{\partial x'} + \frac{\partial \Omega}{\partial x''} + \frac{\partial \Omega}{\partial x'''} \right) + \beta \left( x \frac{\partial \Omega}{\partial x} + x' \frac{\partial \Omega}{\partial x'} + x'' \frac{\partial \Omega}{\partial x''} + x''' \frac{\partial \Omega}{\partial x'''} \right) + \gamma \left( x^2 \frac{\partial \Omega}{\partial x} + x'^2 \frac{\partial \Omega}{\partial x'} + x''^2 \frac{\partial \Omega}{\partial x''} + x'''^2 \frac{\partial \Omega}{\partial x'''} \right) = 0$$

$\alpha, \beta, \gamma$  arbitrary const.  $\alpha = 0$  to coeff.  $k \neq 0 \rightarrow$

$$\frac{\partial \Omega}{\partial x} = 0 \quad (1)$$

$$x \frac{\partial \Omega}{\partial x} = 0 \quad (2)$$

$$x^2 \frac{\partial \Omega}{\partial x} = 0 \quad (3)$$

$\therefore \Omega = \text{const.}$  i.e. diff. eq. solution is

(1)  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$

$$dx = dx' = dx'' = dx'''$$

$$u' = x' = x, \quad u'' = x', \quad u''' = x \quad \text{const}$$

$$\Omega = \Omega(u', u'', u'''), \quad \# 3 \text{ pts}$$

4 v  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$

$$u' \frac{\partial \Omega}{\partial u'} + u'' \frac{\partial \Omega}{\partial u''} + u''' \frac{\partial \Omega}{\partial u'''} = 0$$

$$\frac{du'}{du'} = \frac{du''}{du''} = \frac{du'''}{du'''} = 1$$

$$\log u' = \log u'' = \log u''' = \log c$$

$$v = \frac{u''}{u'} = \text{const.}$$

$$2 u w = \frac{u'''}{u'} = \text{const.}$$

$$\therefore \Omega = \Omega(v, w), \quad \# 2 \text{ pts}$$

4 v  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$

$$(v-1)v \frac{\partial \Omega}{\partial v} + (w-1)w \frac{\partial \Omega}{\partial w} = 0$$

$$\frac{dv}{(v-1)v} = \frac{dw}{(w-1)w}$$

$$\frac{v-1}{v} = \frac{w-1}{w} = \text{const.}$$

$$\Omega = \Phi \left( \frac{v-1}{v}, \frac{w-1}{w} \right) \quad \Phi, \text{ arbitrary f}$$

$$\therefore \Omega = \Phi \left( \frac{x''-x'}{x''-x}, \frac{x'''-x''}{x'''-x} \right)$$

4 v  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$

4  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$  i.e.  $\Omega = \text{const.}$

Klein's general proj.  $n = 3$  in  $\mathbb{P}^3$ ,  $5 \neq 2$   
 4 pts, inv. double ratio = abstracting  $f \rightarrow$   
 Proj. double ratio in  $\mathbb{P}^1$  case = as  $\rightarrow$

6.8. Klein's principle for classification of geometry

Klein 1872 - Vergleichende Betrachtung in

neue geom. Forschungen (Erlangen, 1872)  
 of cont. group & mixed group  $n=1, 2, 3, \dots$

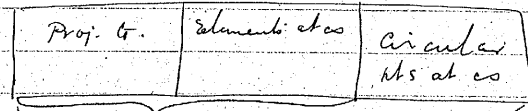
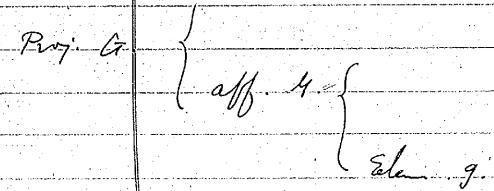
Hauptgruppen invariant in figure  $n=1, 2, 3, \dots$   
 Geometry of group  $n=1, 2, 3, \dots$  inv.  $t$

$n=1, 2, 3, \dots$  collineation, correlation  
 in the mixed group  $n=2, 3, \dots$  inv. theory & project.

geom.  $n=1, 2, 3, \dots$  = affine H. in cont. group  
 $n=1, 2, 3, \dots$  invariant theory & affine geom.  $n=1, 2, 3, \dots$

mot., symmetries, circles to  $n=1, 2, 3, \dots$  mixed

group (Hauptgruppen)  $n=1, 2, 3, \dots$  inv. theory & äquivalente Geometrie  $n=1, 2, 3, \dots$  & elementargeom.  $n=1, 2, 3, \dots$



Affine G.  
Elen. G.

Proj. G. parallel  $n=1, 2, 3, \dots$  Heffter  
 Parallelmetrik  $n=1, 2, 3, \dots$  Orthogonalität

Proj. G. + Parallelmetrik = Affine G.  
 Proj. G. + Par. + Orthog. = Elen. G.

(Circular invol.  $q$  + el.  $3, 4, 5, 6, 7, \dots$  in circular pts  
 at  $\infty$  = definition)  $n=1, 2, 3, \dots$  Heffter  $n=1, 2, 3, \dots$

Cayley's A sixth memoir on geometries (1857)  
 Klein's  $n=1, 2, 3, \dots$   $n=1, 2, 3, \dots$  2nd order

curve, theory of proj. G. =  $n=1, 2, 3, \dots$  real, proper  
 to conic  $n=1, 2, 3, \dots$  tangent, pole &

polar, conjugate pts or lines  $n=1, 2, 3, \dots$   $n=1, 2, 3, \dots$

$n=1, 2, 3, \dots$  aff. G. =  $n=1, 2, 3, \dots$  Ellipsen, Hyper.

Parabolae  $n=1, 2, 3, \dots$  2 Centres, diameters,  
 asymptotes  $n=1, 2, 3, \dots$  elen. G.  $n=1, 2, 3, \dots$

$n=1, 2, 3, \dots$  circles, rectangular hyperb.  $n=1, 2, 3, \dots$

2 axes, focus  $n=1, 2, 3, \dots$   $n=1, 2, 3, \dots$

synthetic  $n=1, 2, 3, \dots$  Heffter, Kolbe





Proof. (i) ascript: in  $x, y$  linear eq  
 $u, v = 2$  linear eq.  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  & b.o.  
 then  $1 = \frac{x}{a_1} + \frac{y}{b_1}$  &  $2 = \frac{x}{a_2} + \frac{y}{b_2}$  (1)  
 $\Rightarrow$  (ii)  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   
 $\Rightarrow \alpha_1 u + \beta_1 v + \gamma_1 = 1$  &  $\alpha_2 u + \beta_2 v + \gamma_2 = 2$   
 $\Rightarrow$  (iii)  $\Rightarrow$  (3)  $u x + v y + 1 = 0$  & (4)  $u x + v y + 1 = 0$   
 $\Rightarrow$  (3)  $\Rightarrow$  (4)  $\Rightarrow$   $\frac{A_1 u + B_1 v + C_1}{A_2 u + B_2 v + C_2} = 1$

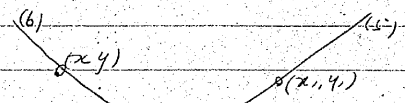
$$y = \frac{B_1 x + A_1 v + C_1}{C_1 x + C_2 v + C_3} \Rightarrow \frac{A_1 u + B_1 v + C_1}{A_2 u + B_2 v + C_2} = 1$$

we  $u, v$  linear eq  $\Rightarrow$  9 fixed pt  $\Rightarrow$  B  
 flat pencil  $\Rightarrow$  pt  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   
 (4)  $x, y, z$   
 $x_1 = \frac{A_1 u + B_1 v + C_1}{A_2 u + B_2 v + C_2}$  &  $y_1 = \frac{A_2 u + B_2 v + C_2}{A_3 u + B_3 v + C_3}$

in (2)  $\Rightarrow$   $A_1 = \alpha_1, B_1 = \beta_1$

Def. we then  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   
 rel: Möbius Allgemeine Dualität  
 (18-7)  $\Rightarrow$  Correl.  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$

(1)  $\Rightarrow$  (4)  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$   
 (5)  $(a_1 x + b_1 y + c_1) x + (a_2 x + b_2 y + c_2) y + (a_3 x + b_3 y + c_3) z = 0$   
 $\Rightarrow$   $(x, y, z)$   $\Rightarrow$   $(x, y, z)$   $\Rightarrow$  bilinear rel.  $\Rightarrow$  3  
 all Dualität: Aquation directrix  $\Rightarrow$  3  
 (Plücker) (generativ eq.  $\Rightarrow$  7 em.)  
 pt  $(x, y)$   $\Rightarrow$  fix  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   
 cord  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   
 (6)  $(a_1 x + a_2 y + a_3) x + (b_1 x + b_2 y + b_3) y + (c_1 x + c_2 y + c_3) z = 0$   
 1.  $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$   $(x, y)$   $\Rightarrow$  current end  
 1. line  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$



get eq  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$   
 then  $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$

### 70. Particular Cases

gen. eq.  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$  symmetrical  
 $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$  transform  $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$   
 $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$   
 dual  $\Rightarrow$  involutory, involutional  
 $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$   
 $\frac{x}{a_1} + \frac{y}{b_1} = 1$  &  $\frac{x}{a_2} + \frac{y}{b_2} = 2$   $\Rightarrow$   $\frac{x}{a_1} + \frac{y}{b_1} = 1$

involut. dualif. conditi. = ...

I (5). (6) is

$$a_1 = b_1, a_2 = c_1, b_3 = c_2$$

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = 0 \text{ symmetric + 3 = 0 + 0}$$

II.  $a_1 = b_1 = c_1 = 0, a_2 = -b_2, a_3 = -c_2, b_3 = -c_3$

III.  $a_1 = 0, a_2 = 0, a_3 = 0$

IV.  $a_1 = 0, a_2 = 0, a_3 = 0$

$$(-b_1 y - c_1)x + (b_1 x - c_1)y + (c_1 x + c_1 y)$$

is identically = 0 vanishes for all x, y

is identically = 0 vanishes for all x, y

can invol. dualif. I = ...

3. I invol. dualif. invol. dualif. invol. dualif.

$$a_1 x^2 + b_1 y^2 + a_2 (y x_1 + x y_1) + a_3 (-x + x_1) + a_4 (y + y_1) + a_5 = 0$$

1 + 2 + 3 + 4 + 5 = 0

$$a_1 X^2 + 2a_2 XY + b_2 Y^2 + 2a_3 X + 2a_4 Y + a_5 = 0$$

in conic = 0 = x, y, polar +

Theorem: reciprocal polar, allgen. Dualif. involuting, in particular case to all D. invol. invol. reciprocal polar (Möbius, dual dualif., Poncelet, reciprocal polar)

$$4. x^2 + y^2 + 1 = 0 \text{ circle} = 0 \text{ } x^2 + y^2 - 1 = 0 \text{ } x^2 + y^2 - 1 = 0$$

Poncelet's circle = 1 = reciprocal polar, then,

is imaginary circle  $x^2 + y^2 + 1 = 0 = 0 = 0$  general eq.

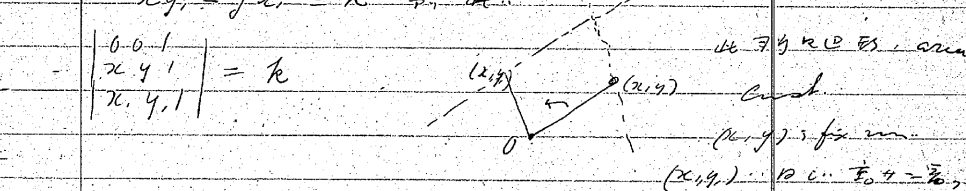
$$x^2 + y^2 + 1 = 0 \text{ } x^2 + y^2 + 1 = 0 \text{ } x^2 + y^2 + 1 = 0$$

Chasles:  $2y \bar{x} = 0$  parabola = 2k =

$$x^2 - y - y_1 = 0 \text{ (Salmon, § 322)}$$

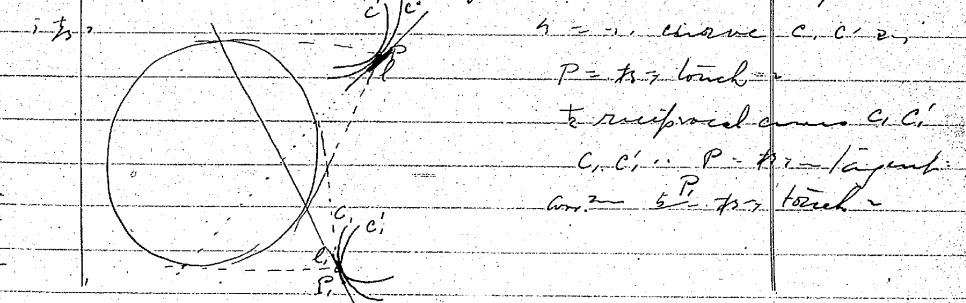
allg. D. invol. invol. invol. invol.

$$x y_1 - y x_1 = k \text{ } x y_1 - y x_1 = k$$



71. Contact transformations

is invol. circle  $x^2 + y^2 - 1 = 0 = 0 = 0$  reciprocal



is invol. circle  $x^2 + y^2 - 1 = 0 = 0 = 0$  reciprocal  
 $P = \dots$  touch  
 to reciprocal axis  $C, C'$   
 $C, C', \dots$  P = ... tangent  
 invol. invol. invol. invol.



(lineal, lines)

C, C' ... P, h tangent,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  line element  $h^2$   
 comm ...  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 C, C' ... lineal,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  lineal  
 h, pt P, h, pole  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  lineal, point P  
 h, pole  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  h, h,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  rel. on  $\frac{1}{2} \frac{d^2}{dx^2}$   
 poles reciprocal ... lineal,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  transform  
 mat +  
 lineal ... pt  $(x, y)$ , direct  $y' (= \frac{dy}{dx}) =$   
 2nd ... rough ... lineal ... coord ...  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 3.2 ... point ... lineal ... plane ... element ...  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 3.3 ...  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  lineal, plane, el.  
 3.4 ...  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  lineal,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  transform,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 Lie (1870) +  
 $4. x^2 + y^2 - 1 = 0$ , the ...  
 (1)  $2x + y y' - 1 = 0$  ... gen. eq.  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 lineal,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   $(x, y, y')$ ,  $(x_1, y_1, y_1')$   
 (1)  $y_1 = \frac{1}{y} (-2x_1 + 1) = -\frac{2}{y_1} x_1 + \frac{1}{y_1}$   
 (direct)  
 (2)  $y_1' = -\frac{2}{y_1}$   
 or  $y = -\frac{2}{y_1} x + \frac{1}{y_1}$   
 (3)  $y' = -\frac{2}{y}$   
 (1), (2), (3) ...

$x_1 = \frac{-y'}{y - xy'}$ ,  $y_1 = \frac{1}{y - xy'}$ ,  $y_1' = \frac{2}{y}$  ...

lineal, h, h,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  transf,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  poles, recipo  
 cat ... lineal, transf,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$

P  
 $(x_1, y_1, y_1')$   $(x + dx_1, y_1 + dy_1, y_1' + dy_1')$

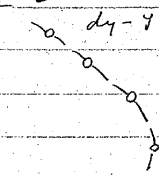
$dx_1 = \frac{-y dy_1 + y_1 dy - y_1^2 dx}{(y - xy_1')^2}$   $dy_1 = \frac{-dy + y' dx + x dy}{(y - xy_1')^2}$

$dy_1 = y_1' dx_1 = \frac{(-y + xy_1') dy + (y - xy_1') y_1' dx}{y(y - xy_1')}$

$\therefore dy_1 - y_1' dx_1 = p(dy - y' dx)$   
 where  $p = \frac{-1}{y(y - xy_1')}$ , diff.  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$

Def. co' lineal  $x, y, y' = \frac{dy}{dx} = 0$ ,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 just as +, h, el. Element-verein (Union-egil)  
 $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   $(x, y)$  on pt  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  lineal,  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$

Thm 1. Element-verein ...  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$  cross, h, el.  $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   
 $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   $\frac{1}{2} \frac{d^2}{dx^2} = \frac{1}{2} \frac{d^2}{dx^2}$   $dy - y' dx = 0$   $dy - y' dx = 0$





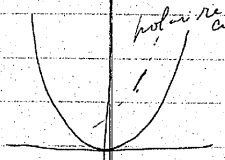
3.10.5 5.1.1. Condition: ... 13.9.0 ...

Hanf. ...

Ex

$2y - x^2 = 0$   $z = z = \text{pole recip}$   
 $y + y' - xz_1 = 0$  gen eq.

$z_1 = y'$ ,  $y_1 = x y' - y$ ,  $y_1' = x$



polynomial

$(x, y, z)$

diff eq. ...

Legendre ...

Clairaut's eq. ...

$y = x y' + f(y_1)$

parabola ...

$y_1 + f(y_1) = 0$

to pole recip. ...

admit ...

Let contact K. ...

Geom. & Berührgest. I = 2

7.2. Principle of duality in space

space, duality: plane, duality ...

(x, y, z) pt coord. (u, v, w) plane coord.

$ux + vy + wz + 1 = 0$

ally ...

$u = \frac{ax + by + cz + d}{ax^2 + by^2 + cz^2 + d}$ ,  $v = \frac{ax}{ax^2}$ ,  $w = \frac{az}{az^2}$

$x_1 = \frac{A_1 u + B_1 v + C_1 w + D_1}{A_4 u + B_4 v + C_4 w + D_4}$   $y_1 = \dots$   $z_1 = \dots$

gen eq.  $(a_1 x + b_1 y + c_1 z + d_1) + (a_2 x + b_2 y + c_2 z + d_2) z_1 + (a_3 x + b_3 y + c_3 z + d_3) z_1^2 + (a_4 x + b_4 y + c_4 z + d_4) = 0$  (Möbius (8.3.3))

de duality ... involutory ...

I

a	b	c	d
a	b	c	d
a	b	c	d
a	b	c	d

symmetric ...

2nd order surface ... pole reciprocal ...

II the determinant ...

0	-C	B	-D
C	0	-A	E
-B	A	0	F
-D	-E	-F	0

gen eq. ...

$(-Bz - Cy + D)x_1 + (Cz - Ax + E)y_1 + (Ay - Bx + F)z_1 = (Dz + Ey + Cx)$

...  $x_1 = x$ ,  $y_1 = y$ ,  $z_1 = z$  ...

... plane ...

... plane ...

... null-syst





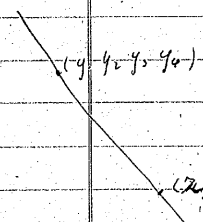








current coord:  $(x_1, z_1, x_2, z_2)$



$$p_{ik} = \begin{vmatrix} y_i & y_k \\ z_i & z_k \end{vmatrix} \quad (i, k = 1, 2, 3, 4)$$

i.e.

$$p_{ii} = 0, \quad p_{ik} = -p_{ki}$$

i.e.  $p_{12}, p_{13}, p_{14}, p_{23}, p_{24}, p_{34}$

$p_{12}, p_{13}, p_{14}, p_{23}, p_{24}, p_{34}$

6 quantities, was point  $y, z$  is line  
homogeneous coordinates 1-2-3-4

3-4 is not, 6 is independent

$$p_{12}p_{34} + p_{13}p_{24} + p_{14}p_{23} = 0 \quad \text{if } i =$$

2-3 coord: Grassman 1844

it is the plane, 2 is a line, having

coord:  $i, j, k$

$\Rightarrow$  plane  $u_1, u_2, u_3, u_4$  current coord

$v_1, v_2, v_3, v_4, w_1, w_2, w_3, w_4$  plane

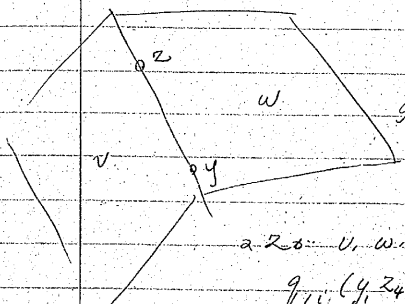
$$q_{ik} = \begin{vmatrix} v_i & v_k \\ w_i & w_k \end{vmatrix} \quad q_{ii} = 0, \quad q_{ik} = -q_{ki}$$

$q_{12}, q_{13}, q_{14}, q_{23}, q_{24}, q_{34}$

5 is not, plane, 2 is line, having coord

cf. Plücker, 1865 = 5-1-7

5-1-7:  $p_1, p_2, p_3, p_4, p_5, p_6, p_7$



$y_0 = v_1 t + z_0 = \text{const}$

$$v_1 y_1 + v_2 y_2 + v_3 y_3 + v_4 y_4 = 1$$

$$w_1 y_1 + w_2 y_2 + w_3 y_3 + w_4 y_4 = 0$$

$$-(v_1 w_1 - w_1 v_1) y_1 + \dots = 0$$

$$z_k \begin{vmatrix} q_{1i} y_i + q_{2i} z_i + q_{3i} y_i^2 + q_{4i} z_i^2 \\ q_{1i} z_i + q_{2i} z_i^2 + q_{3i} z_i^3 + q_{4i} z_i^4 \end{vmatrix} = 0$$

$$q_{1i} (y_i z_i - z_i y_i) + \dots = 0$$

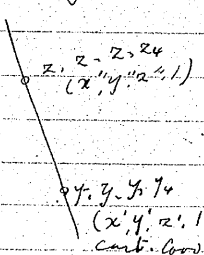
$$q_{1i} p_{ik} + q_{2i} p_{ik} + q_{3i} p_{ik} + q_{4i} p_{ik} = 0$$

i, k = 1, 2, 3, 4 = 5 linear eq. 5-1-7 is 5-1-7

$$\frac{q_{12}}{p_{34}} = \frac{q_{13}}{p_{24}} = \frac{q_{14}}{p_{23}} = \frac{q_{23}}{p_{14}} = \frac{q_{24}}{p_{13}} = \frac{q_{34}}{p_{12}}$$

the = p. 5-1-7 is 5-1-7

having line and 6 numbers



$$p_{12} = x_1 y_1 - y_1 x_1$$

$$p_{13} = y_1 z_1 - z_1 y_1$$

$$p_{21} = z_1 x_1 - x_1 z_1$$

$$p_{22} = x_1^2 - z_1^2$$

$$p_{32} = y_1^2 - z_1^2$$

$$p_{43} = z_1^2 - z_1^2$$

$$\begin{aligned}
 x &= r z + p, \quad y = s z + \sigma = a v \\
 x' &= r' z' + p, \quad y' = s z' + \sigma \\
 x'' &= r'' z'' + p, \quad y'' = s z'' + \sigma \\
 r &= \frac{x' - x''}{z' - z''} = \frac{p_{14}}{p_{45}}, \quad s = \frac{y' - y''}{z' - z''} = \frac{p_{24}}{p_{34}} \\
 p &= \frac{z' x'' - x' z''}{z' - z''} = \frac{p_{11}}{p_{14}}, \quad \sigma = -\frac{y' z'' - z' y''}{z' - z''} = \frac{p_{21}}{p_{34}} \\
 \eta &= s p - \sigma \sigma = \frac{p_{24} p_{31} - p_{14} p_{32}}{p_{34}^2} = \frac{p_{24}}{p_{34}}
 \end{aligned}$$

non-homog coord; homog.  $z, z', z''$   $\rightarrow z, z', z''$   $\rightarrow z, z', z''$   
 $p_{14}$   $a v$   $13 \cdot 5 = \dots$   $10, 2, 1, 2$

26 Proj. transformation

space  $\rightarrow$  coll. homog point coord  
 $(x, x_2, x_3, x_4) \rightarrow e_1$

$$x_i = a_{i1} x_1 + \dots + a_{i4} x_4 \quad (i = 1, \dots, 4)$$

coll. in  $y$

$$y_i = a_{i1} y_1 + \dots + a_{i4} y_4$$

$$z_i = a_{i1} z_1 + \dots + a_{i4} z_4$$

$$p_{ik} = \begin{vmatrix} y_i & y_k \\ z_i & z_k \end{vmatrix} = \sum_{\mu, \nu} a_{i\mu} a_{k\nu} \begin{vmatrix} y_\mu & y_\nu \\ z_\mu & z_\nu \end{vmatrix}$$

$$p_{ik} = \sum_{\mu, \nu} a_{i\mu} a_{k\nu} p_{\mu\nu}$$

linear transform  $\rightarrow$

$$y' = \frac{p_{14}}{p_{34}}, \quad s' = \frac{p_{24}}{p_{34}}$$

$$y = \frac{\sum a_{1\mu} a_{2\nu} p_{\mu\nu}}{\sum a_{1\mu} a_{3\nu} p_{\mu\nu}} = \frac{\text{lin. f. of } (x, s, p, \sigma)}{\text{lin. f. of } (x, s, p, \sigma, \eta)}$$

$$s' = \dots$$

hence  
 these  $\rightarrow$   $\phi(p_{ik}) = 0$  &  $\phi(x, s, p, \sigma, \eta) = 0$   
 coll. in  $\mathbb{P}^4$   $\rightarrow$  Plücker  $\rightarrow$   $\dots$

Remark plane  $(x, x_2, x_3)$   $\rightarrow$   $(x, x_2, x_3)$   $\rightarrow$   $(x, x_2, x_3)$   
 $x_3 = 0$   $\rightarrow$   $\dots$   $\rightarrow$   $\dots$   
 coll. affines  $\rightarrow$   $x^2 + x_2 = 0$   
 $x_3 = 0$   $\rightarrow$   $\dots$   $\rightarrow$   $\dots$   
 dimens  $2 = 5$   $\rightarrow$   $\dots$   
 proj. gen  $\rightarrow$   $\dots$   
 $p_{14} p_{34} + p_{13} p_{24} + p_{12} p_{34} = 0$   $\rightarrow$   $\dots$   
 proj. gen  $\rightarrow$   $\dots$

17. Line complex, congruence, ruled surface

pt space (x, y, z) & t = 0 pt.  $co^3$   $co^2$   $co^1$   $co^0$   
 coord:  $B = F = 0$   $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 $F_1 = 0, F_2 = 0, F_3 = 0$   $co^3$   $co^2$   $co^1$   $co^0$

i = dual - plan space (u, v, w, u')  $co^3$   $co^2$   $co^1$   $co^0$   
 $co^3$ , pla =  $co^3$

$F = 0$   $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 $F_1 = 0, F_2 = 0, F_3 = 0$   $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

correspond in lin space

$co^4$   $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

$F_1 = 0, F_2 = 0, F_3 = 0$   $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

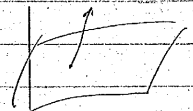
line congruence (Chapman)

$F_1 = 0, F_2 = 0, F_3 = 0$   $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

ruled surface  $co^3$   $co^2$   $co^1$   $co^0$

complex  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

ratie complex  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$



surface, ampt  $co^3$   $co^2$   $co^1$   $co^0$   
 $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 line congruence  $co^3$   $co^2$   $co^1$   $co^0$   
 normal eqn  $co^3$   $co^2$   $co^1$   $co^0$

Optics  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

line congruence, theory  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 Hamilton (1840)  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 optics  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

18. Linear complex

There are 1. linear complex null lin  $co^3$   $co^2$   $co^1$   $co^0$   
 line complex  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

Null l. eq  $co^3$   $co^2$   $co^1$   $co^0$   
 $A_0 = B_0 p + C(s, p - r_0) + D_0 + E_0 s + G_0 = 0$

linear eq  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$   
 $A \frac{p_1}{p_2} + B \frac{p_1}{p_3} + C \frac{p_1}{p_4} + D \frac{p_1}{p_4} + E \frac{p_1}{p_4} + G = 0$

$a_1 p_1 + a_2 p_2 + a_3 p_3 + a_4 p_4 + a_5 p_1 + a_6 p_2 + a_7 p_3 + a_8 p_4 = 0$

linear eq  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

There are 1.  $co^3$   $co^2$   $co^1$   $co^0$   $co^3$   $co^2$   $co^1$   $co^0$

$$p_{11}p'_{11} + p_{12}p'_{12} + p_{13}p'_{13} + p_{21}p'_{21} + p_{22}p'_{22} + p_{23}p'_{23} = 0$$

$\therefore p \cdot p' = y \cdot z \cdot p' \cdot y' \cdot z' + \dots$   
 $p \cdot p' = 0 \dots$  on plane  $= z \cdot z' + \dots$

$$\begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ z_1 & z_2 & z_3 & z_4 \\ y'_1 & y'_2 & y'_3 & y'_4 \\ z'_1 & z'_2 & z'_3 & z'_4 \end{vmatrix} = 0$$

$\therefore$  Laplace's development

Theorem 3 - linear complex (ap) =  $\sum_{i,j} a_{ij} p_i p_j = 0$   
 is a linear complex if a certain line is met  
 on a surface

$$a_{11}a_{22} + a_{12}a_{21} + a_{13}a_{31} = 0$$

Linear complex:  $B = 0$  for  $p_i p_j$  in an

$$p_1 p_2 + \dots = 0$$

$$p_1 p_2 + p_2 p_3 + p_3 p_1 = 0$$

$$p_3 = k \cdot a_{11}$$

$$p_1 p_2 + p_2 p_3 + p_3 p_1 = 0$$

$$a_{22}a_{33} + a_{23}a_{32} + a_{31}a_{13} = 0$$

$\therefore a_{11} = 1/2 \dots$  (a) in linear coord.  $x, y, z$

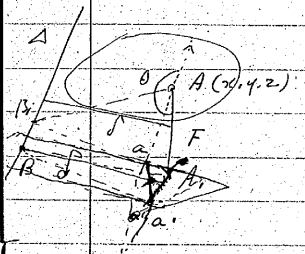
$l, m, n$   $l, m, n$

Def of linear complex:  $\dots$   
special complex  $\dots$

Theorem 4  $A = a_{11}a_{22} + a_{12}a_{21} + a_{13}a_{31} + \dots$  Coll.  $\dots$   
 is invariant  $\dots$

Def  $A$  is linear complex, invariant  $\dots$   
 is special complex - constant  $\dots$

Ex Statics - force application



$A$  - resultant force act

$F$  - component  $x, y, z$

$d = 1$  - angle between force and  $x$ -axis

$d = 2$  - force moment

moment =  $F \cdot d \cdot \sin \theta$

$d$ : dist.  $F$  to  $x$ -axis

$\theta$ :  $F$  to  $x$ -axis angle

$d$  is  $\dots$   $AA'$  is  $\dots$   $a =$  parallel plane  $\dots$

$A$  is  $\dots$   $B$  is  $\dots$   $L$  is  $\dots$   $d$  is  $\dots$

$B = \dots$   $a =$  normal plane;  $AA'$  is normal to normal plane  $\dots$

$AA'$  is orthogonal projection  $\dots$   $AA' = \dots$

$\therefore \dots$   $d = \dots$

$$d = \dots = \text{vol}(AA', B, B_1) = \text{vol}(aa, B, B_1)$$

$$= \frac{1}{3} (\frac{1}{2} a \cdot d \cdot \dots)$$

$$= \frac{1}{6} d \cdot \dots$$

$$\text{moment} = \frac{1}{6} \text{vol}(AA', B, B_1)$$

$B, B_1$

$$A(x, y, z), A_1(x + X, y + Y, z + Z), B(x', y', z'), B_1(x', y', z')$$

$L = yZ - zY, M = zX - xZ, N = xY - yX + \vec{e}_3$   
 rigid body force in  $X, Y, Z$  in  $L, M, N$  in  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

$$\pm 6 \text{ vol. } (A, A, B, B, \dots) = \begin{vmatrix} x & y & z & 1 \\ x' & y' & z' & 1 \\ x'' & y'' & z'' & 1 \end{vmatrix}$$

$$= \pm [(x'' - x')L + (y'' - y')M + (z'' - z')N + (y'z'' - y''z')X + (z'x'' - z''x')Y + (x'y'' - x''y')Z]$$

$$\text{Moment} = \frac{L p_{x1} + M p_{y1} + N p_{z1} + X p_{x2} + Y p_{y2} + Z p_{z2}}{\sqrt{p_{x1}^2 + p_{y1}^2 + p_{z1}^2}}$$

then

1857

These (Möbius) force  $\vec{e}_1, \vec{e}_2, \vec{e}_3 +$  moment  $\vec{e}_1, \vec{e}_2, \vec{e}_3$   
 $0 + i$  constant line  $\Delta$ : null conic  $\vec{e}_1, \vec{e}_2, \vec{e}_3$   
 Null conic: Null moment  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

### 7.9. Linear congruence

$\infty^2$  to  $\infty^1$  line, totality: linear congruence  
 $\infty^2$  line conic

$$(ap) + x(bp) = 0$$

$x$ , arbitrary const  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

the complex: special complex  $\vec{e}_1, \vec{e}_2, \vec{e}_3 = 0$

$$A + MA + BX = 0$$

$$A = a_{11}a_{22} + a_{12}a_{21} + a_{13}a_{31} + a_{14}a_{41} + a_{15}a_{51} + a_{16}a_{61} + a_{17}a_{71} + a_{18}a_{81} + a_{19}a_{91} + a_{10}a_{10}$$

$$M = a_{11}b_{22} + a_{12}b_{21} + a_{13}b_{31} + a_{14}b_{41} + a_{15}b_{51} + a_{16}b_{61} + a_{17}b_{71} + a_{18}b_{81} + a_{19}b_{91} + a_{10}b_{10}$$

the quad. eq. roots  $\lambda, \lambda'$

$$(ap) + \lambda(bp) = 0$$

$$(ap) + \lambda'(bp) = 0$$

$\lambda$  linear congruence  $\vec{e}_1, \vec{e}_2, \vec{e}_3 = 1/2 \vec{e}_1, \vec{e}_2, \vec{e}_3$  special complex  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  congruence  $\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$

Then  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  congruence  $\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$

$\Rightarrow$  fixed  $\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$ ,  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

Con  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  line conic  $(ap) = 0, (bp) = 0, (cp) = 0$

the  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  conic, line conic, ruled surface

$\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$ ,  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

### 80. Quadratic complex

$$\Phi_2(p, p) = 0 \text{ } \vec{e}_1, \vec{e}_2, \vec{e}_3 \text{ quadratic homog. eq. } \vec{e}_1, \vec{e}_2, \vec{e}_3$$

complex  $\vec{e}_1, \vec{e}_2, \vec{e}_3 \in$  plane geom  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  degree curve

$\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$  a space geom  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  quad. surface

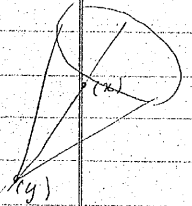
$\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$  line geom  $\vec{e}_1, \vec{e}_2, \vec{e}_3 = \vec{e}_1, \vec{e}_2, \vec{e}_3$

$\vec{e}_1, \vec{e}_2, \vec{e}_3$  quad. complex  $\vec{e}_1, \vec{e}_2, \vec{e}_3$  systematic study

Plücker (1838-9) (Nouvelles Geom.) Klein (1868-70)

(Klein: Line conic  $\vec{e}_1, \vec{e}_2, \vec{e}_3$ , imaginary unit  $\vec{e}_1, \vec{e}_2, \vec{e}_3$ )  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

3 space, simple (y, y, y, y) in complex plane  
 pt. (x, y) = (x, x, x, x) in

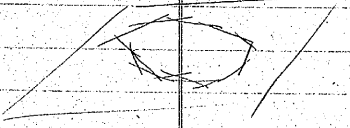


$\phi(x, y) = 0$   
 1st eq.  $x, x, x, x = 2$  2nd deg.  
 homog. eq.  $x, x, x, x = 2$  2nd deg.  
 surface,  $2, 2, 2, 2 = 2$  2nd deg.  
 2nd deg. cone  $1, 3, 4, 2 = 2$  2nd deg.  
 dual = one plane  $(x, y) = 0$

to cover  $(u, v, u, v)$  in plane  $u, v$  complex line  
 curve  $u, u, u, u = 2$

$\psi(u, v) = 0$   $\psi(u, v) = 0$  1st deg.

1st  $u, u, u, u = 2$  2nd deg. homog. eq.  $u, v, u, v = 2$   
 to line  $u, v$  on plane  $u, v = 2$  2nd deg. line  
 2nd class, curve, envelope  $u, v = 2$



There is quad. complex = 2, 2 simple in line  
 2nd and curve, generate in plane  $u, v$   
 line 2nd deg. curve, envelope

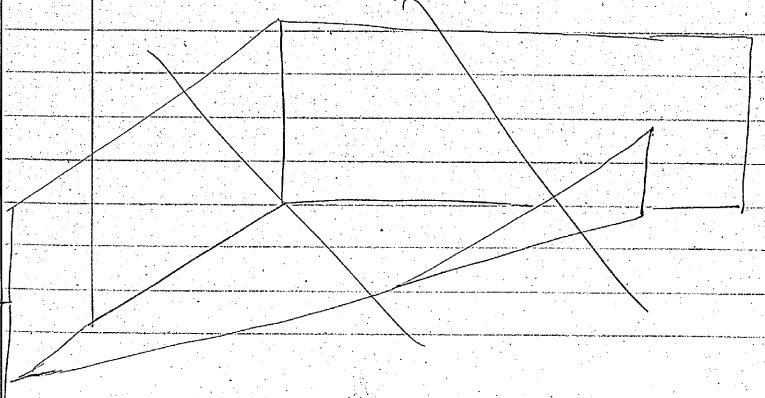
Remark  $u, v = 2$  with  $u, v = 2$  then, proof  
 in the deg. complex = apply  $u, v = 2$

flat pencil or one point in a (null system)

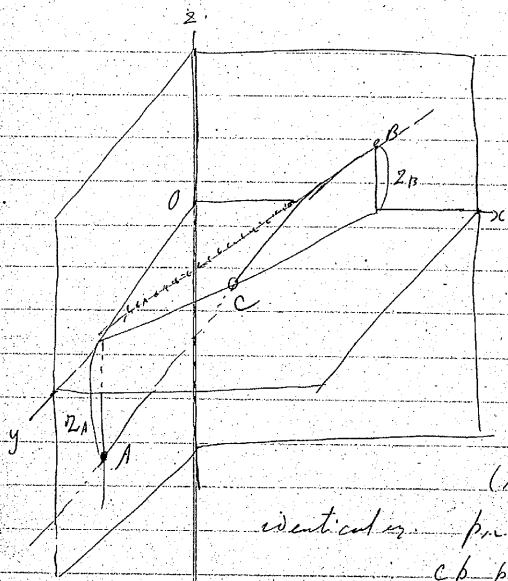
to quad. complex = 2, 2 2nd deg. curve  
 1st  $u, v = 2$  plane = break up to pt. 3. singular  
 pt. 1st quad. complex, 2, line  $u, v = 2$  2nd deg. pt.  
 1st  $u, v = 2$  2nd deg. pt. focus, conic surface  
 1st  $u, v = 2$  Kummer's surf.  $u, v = 2$  (1864) 2nd  
 surf. 16 nodes (double point) in  $u, v = 2$   
 quartic surface  $u, v = 2$  (1862) (1864)

quad. complex  $u, v = 2$  2nd deg. curve, 2nd deg. curve  
 particular case  $u, v = 2$

line aggregate in tetrahedron  $u, v = 2$   
 2nd deg. pt. double ratio constant given  
 value  $u, v = 2$  2nd deg. curve, aggregate  
 1st  $u, v = 2$  2nd deg. curve,  $x=0, y=0, z=0$  plane  
 at  $u, v = 2$







$$\frac{APC}{BC} = \frac{AD}{BD} = \frac{APC}{BC}$$

h.e. eq.

$$x = \lambda z + \mu, \quad y = \lambda z + \nu$$

$$\frac{AP}{BC} = \frac{zA}{zB} = \frac{-\frac{\lambda}{\mu}}{-\frac{\lambda}{\nu}} = \frac{\lambda \nu}{\lambda \mu}$$

$$\frac{\lambda \nu}{\lambda \mu} = \text{const} = \frac{a-c}{b-c}$$

at b, c, + arbitrary

const. i.e. s

$$(b-c)p_{12}p_{13} + (a-c)p_{12}p_{14} = 0$$

identical eq.  $p_{12}p_{13} + p_{12}p_{14} + p_{13}p_{14} = 0$

$$c p_{12}p_{34} = -c p_{12}p_{31} - c p_{12}p_{13}$$

$$a p_{12}p_{23} + b p_{12}p_{21} + c p_{12}p_{14} = 0 \quad (a + b + c)$$

Def. 2. quasi complex tetrahedral complex 13.

is complex,  $\Sigma_2, \Sigma_1, \Sigma_2, \Sigma_3$ . Binet (Théorie d'axes conjugués et de moments d'inertie des corps, 1811-13) + G. 42, 43, 44, 45. H. Müller (1869)

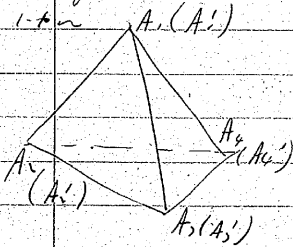
Thm 1.  $\Rightarrow$  span  $\Sigma, \Sigma'$  is collinear

+ 14.  $\Rightarrow$  corresp. pt.  $\Sigma, \Sigma'$  is s.s. h.e. complex tetrah. complex 3-1 (Chasles, 1811)

Proof.  $\Rightarrow$  collinear

$$\begin{aligned} x_i' &= a_i x_i + b_i x_j + c_i x_k + d_i x_l \\ x_j' &= a_j x_j + b_j x_k + c_j x_l + d_j x_i \\ x_k' &= a_k x_k + \dots \\ x_l' &= a_l x_l + \dots \end{aligned}$$

f. dual tetrah. is invariant tets.



$$A_1 \dots x_2 = x_3 = x_4 = 0$$

$$A_2 \dots x_1 = x_3 = x_4 = 0$$

$$A_3 \dots a_1 = a_2 = a_4 = 0$$

$$A_4 \dots a_1 = a_2 = a_3 = 0$$

$$\begin{cases} x_1' = a_1 x_1 \\ x_2' = b_2 x_2 \\ x_3' = c_3 x_3 \\ x_4' = d_4 x_4 \end{cases}$$

is const. syst.  $x, x'$  s.s. h.e. p. 7.14

$$p_{12} = \begin{vmatrix} x_1 & x_1' \\ x_2 & x_2' \end{vmatrix} = \begin{vmatrix} x_1 & a_1 x_1 \\ x_2 & b_2 x_2 \end{vmatrix} = x_1 x_2 (b_2 - a_1)$$

$$p_{14} = x_1 x_4 (d_4 - c_3), \quad p_{13} = x_1 x_3 (c_3 - b_2)$$

$$\therefore \frac{p_{12} p_{34}}{p_{14} p_{23}} = \frac{(b_2 - a_1)(d_4 - c_3)}{(d_4 - a_1)(c_3 - b_2)} = \text{const}$$

is tetrah. comp. 1-1







$\varepsilon = 0$  line at  $\infty \rightarrow \frac{1}{2} \dots$

$$S \equiv \varepsilon(x^2 + y^2) - z^2 = 0 \rightarrow \dots$$

$\varepsilon > 0$  hyperbolic  $m$

$\varepsilon = 0$   $z^2 = 0$ ,  $z = 0$  parabola  $m$

$\varepsilon < 0$  elliptic  $m$

$m =$  line at  $\infty \rightarrow S, P, Q, R, \dots$

$$\Sigma \equiv u^2 + v^2 - \varepsilon w^2 = 0$$

$\varepsilon > 0$  hyp.

$\varepsilon = 0$  par. circular plates  $\left\{ \begin{array}{l} u^2 + v^2 = 0 \\ \dots \end{array} \right.$

$\varepsilon < 0$  ellip.

Klein 1871-72  $\dots$  measurements,  $P, Q$

Euclidean, hyperbolic, elliptic  $\dots$

83. Euclidean geometry

parabolic  $m, \dots$   $k = -\frac{1}{2}(\sqrt{1} - 1)$

$$\Sigma' \equiv u'^2 + v'^2$$

$$\Sigma'' \equiv u''^2 + v''^2$$

$$\Pi = u'u'' + v'v''$$

$$\alpha = -\frac{1}{2} \log \frac{(u'u'' + v'v'') + i(u'u'' - v'v'')}{(u'u'' + v'v'') - i(u'u'' - v'v'')}$$

$$(u'u'' + v'v'') + i(u'u'' - v'v'') = r e^{i\theta} = r(\cos\theta + i\sin\theta)$$

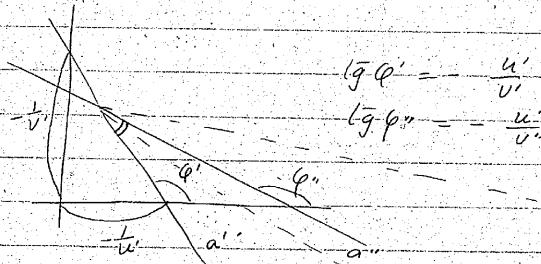
$$(\dots) - i(\dots) = r(\cos\theta - i\sin\theta)$$

$$\alpha = -\frac{i}{2} \log e^{2i\theta} = -\frac{i}{2}(2i\theta) = \theta$$

$$\phi'_{uv} = x \cos\theta = u'u'' + v'v''$$

$$x \sin\theta = u'u'' - v'v''$$

$$\tan\theta = \frac{(-\frac{u''}{v''}) - (-\frac{u'}{v'})}{1 + (-\frac{u'}{v'})(-\frac{u''}{v''})}$$



$$\tan\phi' = \frac{u'}{v'}$$

$$\tan\phi'' = -\frac{u''}{v''}$$

$$\tan\theta = \tan(\phi'' - \phi')$$

$\alpha = \theta$   $a', a''$   $\dots$  Euclidean angle  $\phi$

Laguerre, Klein (1852)  $\dots$  circular plates, absolute circle  $\dots$  measurements in angle  $\dots$

$m = k + 1, 8; \dots$

$$K = -\frac{1}{2\sqrt{8}} \dots \varepsilon = 0 \dots$$

$$D = \dots \left\{ -\frac{1}{2\sqrt{8}} \log \frac{P + \sqrt{P^2 - S^2}}{P - \sqrt{P^2 - S^2}} \right\}$$

$$S' \equiv \varepsilon(x^2 + y^2) - z^2$$

$$S'' \equiv (x^2 + y^2) - z^2$$

$$P \equiv \varepsilon(x^2 + y^2) - z^2$$



$$\frac{D}{2K} = \frac{e}{2} = \frac{-D}{2K} = \sqrt{\frac{P^2 - S'S''}{S'S''}}$$

$$\frac{D}{2K} = i \sqrt{\frac{P^2 - S'S''}{S'S''}}$$

hyperbolic plane,  $t = \sqrt{2} \text{ or } 1 = \frac{1}{2} \text{ or } 1$

$$(x, y, z) \quad x + dx, \quad y + dy, \quad z + dz \quad z = 1, \quad dz = 0$$

distance  $ds = \dots$

$$\frac{ds}{2K} = \frac{1}{2} \left( \frac{ds}{2K} \right)^2 = i \sqrt{\frac{[x(x+dx) + y(y+dy)] - z(z+dz)]^2 - S'S''}{[x(x^2+y^2) - z^2][x(x+dx) + y(y+dy)]}}$$

$$S = x(x^2 + y^2) - z^2$$

$$S' = 2[x(x+dx) + y(y+dy)] - 2(z+dz)$$

$$P = 2[x(x+dx) + y(y+dy)] - 2(z+dz)$$

higher order infinitesimal

$$\frac{ds^2}{4K^2} = \frac{[x(x+dx) + y(y+dy)] - z(z+dz)]^2 - S'S''}{[x(x^2+y^2) - z^2]^2}$$

$$\frac{ds^2}{4K^2} = \frac{[x^2 dx^2 - 2x dx dz + z^2 dz^2 + y^2 dy^2 - 2y dy dz + z^2 dz^2] + [x(x+dx) + y(y+dy)] - z(z+dz)}{[x(x^2+y^2) - z^2]^2}$$

binomial expansion

$$\frac{ds^2}{4K^2} = \frac{[x^2 dx^2 - 2x dx dz + z^2 dz^2 + y^2 dy^2 - 2y dy dz + z^2 dz^2]}{[x(x^2+y^2) - z^2]^2}$$

$z = 1, dz = 0$  Carliora end

$$ds^2 = 4K^2 \frac{dx^2 + dy^2}{[x(x^2+y^2) - 1]^2}$$

to find differential quadratic form

curvature negative constant

Dif gen = ...

hyperbolic plane negative constant curvature

surfaces deformable

hyperbolic plane geodesic

Beltrami (1866)

pseudo-spherical surface

deformable

angular points

Hilbert (1901) Holmgren (1902)

elliptic geometry

absolute curve imaginary

real point



Thus it happens that geodesics, though on the plane they have only one pt in common, may on the cylinder have an infinite no. of intersections. Somewhat similar to this with rel. fields in spherical & ellipt. geometries. So any one pt in ellipt. space, two pts correspond in spherical space. Thus geodesics, which in spherical space may have two pts in common, can have, in ellipt. space, more than one intersection.

$S' \neq 0, S'' \neq 0$   
 $\log \frac{P+V}{P-V}$  finite  
 what exists on  $R^2$   
 finite & parallel

elliptic geom. Poincaré space  
 pt. order 4  
 mag. curv.  $\frac{1}{R^2}$   
 a harmonic radius  
 pure mag.  $\frac{1}{R^2}$

$$D = iK' \log \frac{P+V \sqrt{P^2-S^2}}{P-V \sqrt{P^2-S^2}}$$

$$ds^2 = -4K'^2 \frac{dx^2 + dy^2}{[2(x^2+y^2)-1]^2}$$

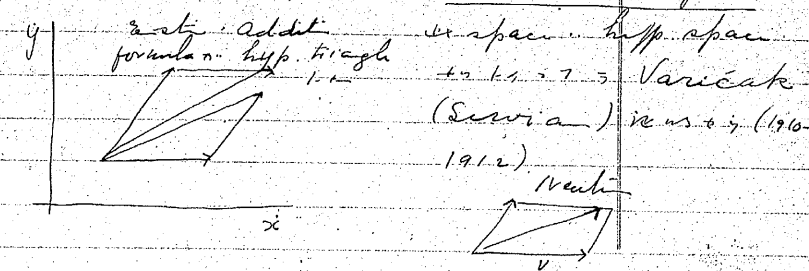
$z < 0, ds^2 > 0$   
 dif. quadratic Kumpmann  
 point curv.  $\frac{1}{R^2}$   
 surf. ellipt. plan  
 spherical diffeomorph.  
 geodesic

diffeomorph. in a geometry of surface sphere =  
 Klein (Lobachevsky, 1899)

space =  $\mathbb{R}^n$   
 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100

absolute curv.  $\frac{1}{R^2}$   
 call. as prop. dist. & length  
 plane, not define its prop. g.  
 Nicht-Euklid. G. Klein - Lieberknecht, Euklid.  
 Funkt. (1899, 1901, 1902) Coolidge, 1940  
 last but one chapter

non-Eukl. g. geometry  
 automorphic f. apply on  $R^2$  = Principle of Relativity  
 velocity component  $z^i_j$  = Cartesian coord. 1. Borel = kinematical space





A straight line, then, is not the shortest distance, but is simply the distance between two pts — so far, this conclusion has stood firm (two pts = 2 unique = 2 straight lines = 1.1.2). But suppose we had two or more curves through two pts, & that all these curves were equivalent *inter se*. We should then say, in accordance with the def. of spatial equality, that the lengths of all these curves were equal. Now it might happen that, although no one of the curves was uniquely determined by the two end-points, yet the common length of all the curves was so determined. In this case, what would hinder us from calling this common length the distance apart, although no unique figure in space corresponded to it? This is the case contemplated by spherical  $\mathbb{R}$ , where, as on a sphere, antipodes can be joined by an infinite no. of geodesics, all of which are of equal length. The difficulty is, therefore, not a purely imaginary one, but one which modern  $\mathbb{R}$  forces us to face.

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It will be remembered that in our a priori proof that two pts must have one definite rel., we held it impossible for these two pts to have, to the rest of space, any rel. which would be unaltered by mot. Now

in spherical space, in the particular case where the two pts are antipodes, they have a rel. unaltered by mot., to the rest of space — the rel. namely, that their distance is half the circumference of the universe. In our former discussion, we assumed that any rel. to outside space must be rel. of position & a rel. of position must be altered by mot. But with a finite space, in which we have absolute magnitude, another rel. becomes possible, namely, a rel. of magnitude. Antipodal pts, accordingly, like coincident pts, no longer determine a unique straight line. And it is instructive to observe that there is, in consequence, an ambiguity in the expression for distance, like the ordinary ambiguity in angular measurement. If  $1/k^2$  be the space constant, &  $d$  be one value for the dist. between two pts,  $2\pi kn + d$ , where  $n$  is any integer, is an equally good value for dist. — is, in short, a periodic function like angle. This and a state of things rather confirms the an.  $\mathbb{R}$ 's my contention, that dist. depends on a curve uniquely determined by two points. For as soon as we drop this unique determination, we are ambiguous creeping into our expression for dist. Dist. still has a set of discrete values, corresponding to

the fact that, given one pt. the straight line is un-  
iquely determined for all other pts. but one, the  
antipodal pt. It is tempting to go on, & say:  
If through every pair of points there were a infi-  
nite no. of the curves used in measuring dist. dist.  
would be able, for the same pair of pts., to take,  
not only a discrete series, but an infinite  
continuous series of values.

This, however, is mere speculation. I come  
now to the piece de resistance of my argument.  
The ambiguity in spherical space arose, as we  
saw, from a rel. of magnitude to the rel. of space  
— such a rel. being unaltered by a rot. of  
the two pts. & therefore falling outside our introductory  
reasoning. But what is this rel. of magnitude?  
Simply a rel. of the dist. between the two pts. to a  
dist. given in the nature of the space in question. It follows  
that such a rel. presupposes a measure of dist.,  
& need not, therefore, be contemplated in any  
argument which deals with the apriori requisites  
for the possibility of definite distances.

I have now shown, I hope conclusively,  
that spherical space affords no object to the apriori  
ty of my axiom. Any two points have one rel., the

dist., which is independent of the rest of space & this rel.  
requires, as its measure, a curve uniquely determined  
by these two pts. I might have taken the bull <sup>by horns</sup>.  
& said: Two pts. can have no rel. but what is  
given by lines which join them, & if they have a  
rel. independent of the rest of space, there must be one  
line joining them which they completely determine. Thus  
James says (Page II. 149-150). 170/

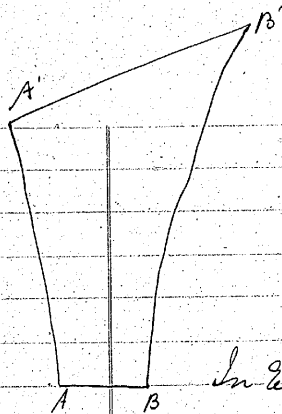
"Just as, in the field of quantity, the rel. between  
two nos. is another no., so in the field of space the rels.  
are facts of the same order, with the facts they relate  
to. When we speak of the rel. of direct. of two pts.  
towards each other, we mean simply the measur-  
y of the line that joins the two pts. together. The line is the rel.  
The rel. of direct. point between the top & bottom pts.  
of a vertical line is that line, & nothing else." 171

Measurement, we may say, is the application of no.  
to continua, or, if we prefer it, the transformation of  
mere quantity into no. of units. Using quantity to  
denote the vague more or less, & magnitude to  
denote the precise no. of units, the problem of  
measurement may be defined as the transformation

of quantity into magnitude.

Now a no. to begin with, is a whole consisting of smaller units, all of these units being qualitatively alike. In ordi. therefore, that a continuous quantity may be expressible as a number, it must, on the one hand, be itself a whole, & thus, on the other hand, be itself divisible into qualitatively similar parts. In the aspect of a whole, the quantity is intensive; in the aspect of an aggregate of parts, it is extensive. A purely intensive quantity, is not numerable — a purely extensive quant. if any such could be imagined, would not be a single quant. at all, since it would have to consist of wholly unaggregated particulars. A measure quant. is a whole divisible into similar parts. But a continuous q. if divisible at all, must be infinitely divisible. For otherwise the pts. at which it could be divided would form natural barriers, & so destroy its continuity. But further, it is not sufficient that there should be a possibility of division ~~of~~ into mutually external parts; while the parts, to be perceptible as parts, must be mutually external parts; while the parts, to be

perceptible as parts, must be <sup>mutually</sup> external, they must also, to be knowable as equal parts, be capable of over-coming this mutual externality. For this, as we have seen, we require equipartition, which involves free mobility & homogeneity — the absence of dur. M. in time, where all other requisites of measurement are fulfilled, renders direct measurement of time impossible. Hence infinite divisibility, free mob. & homogeneity are necessary for the possibility of measurement in any continuous manifold & these, as we have seen, are equivalent to our three axioms. These axioms are necessary, not only for spatial measurement, but for all measurement. The only manifold given in experience, in which these conditions are satisfied, is space. 177



Codrige 48-

5.3

$$\lim_{AB \rightarrow \infty} \frac{m \overset{\text{curvature}}{A'B'}}{m AB} = \phi(x)$$

$$\cos \frac{x}{k} = \phi(x) = 1 - \frac{x^2}{2k^2} + \frac{x^4}{24k^4} - \dots$$

measure of curvature of space

In Euclidean space

$$\frac{1}{k^2} = 0 \quad k = \infty$$

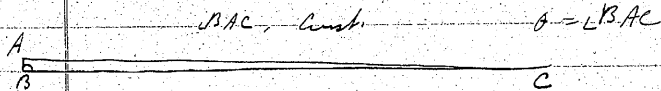
$$\cos \frac{x}{k} = \cos 0 = 1 = \phi(x) \text{ constant}$$

Hyperbol. sp.  $\frac{1}{k^2} < 0$

$$k = iK$$

$$\phi(x) = \cosh\left(\frac{x}{K}\right)$$

Ellipt. sp.  $\frac{1}{k^2} > 0$



$$\lim_{AC \rightarrow 0} \frac{AB}{AC} = f(0) = \cos 0$$

a, b, c measures of opposite sides of ABC

$$\cos \frac{b}{k} = \cos \frac{a}{k} \cos \frac{c}{k} \quad \text{expanded in}$$

Euclid. case  $b^2 = a^2 + c^2$ , Pythagorean thm.

Euclid. Axiom 1, 2, 3, 4, 5, post. parallel-postulate (Axiom 11 or 12, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100)

The measurement of angles is independent of the theory of parallels. Vertically opposite angles are equal; the sum of the four angles made by two intersecting angles lines is an absolute constant, & one quarter of this is a right angle. An absolute unit of angle, therefore, exists. A "flat angle", which is equal to two right angles, is generally denoted by the symbol  $\pi$ . Through a given pt. only one perpendicular can be drawn to a given straight line, the usual construct for this being always possible. But it is necessary to warn the reader that  $\pi$  does not stand for the ratio of the circumference of a circle to its diameter, for in non-Eucl. geom. this ratio is not constant; & the radian, unit of angle, in terms of which a flat angle is represented by the no.  $\pi$ , does not admit of the families constructed by means of a circle. Srinivasa, 38.



- rel. betw.
- 3 cases of hyp. H. (two straight lines)
- (1) Intersecting, & have a real angle of intersect, but no common perpendicular.
  - (2) Non-intersecting, & have a real shortest dist or common perpendicular, but no real angle.
  - (3) Parallel, with a zero angle & zero shortest dist or common perp. at  $cs$ .  
(equidistant lines ... & c.)

In hyp. H. on every line there are two pts at  $cs$ , & the assemblage of pts at  $cs$  in a plane is a curve of the 2nd degree or conic, since it is met by any line in two pts. In three dim the assemblage is a surface of the 2nd degree or quadric. This figure, the assemblage of all the pts at  $cs$ , is called the Absolute.

When two pts at  $cs$  approach coincidence, the line determined by them becomes a tangent to the Absolute. No such a line is called a line at  $cs$ . Similarly we obtain planes at  $cs$ , which are tangents to planes to the Absolute.

In Euclid 9, there is just one parallel

through a given pt. to a given line in a plane, & the two pts at  $cs$  upon a line coincide. The assemblage of pts at  $cs$  in a plane then reduces to a double line, the line at  $cs$ , which is a degenerate case of a conic. There is in this case only one real line at  $cs$ , but any line whose equation in rectangular coord. is of the form  $x+iy+c=0$  is at an infinite dist from the origin, since  $1+i^2=0$ , & the assemblage of these lines consists of two ming pencils. The equation of the line at  $cs$  is  $x=0$  or  $y=0$  & the equations of the two pencils are  $w+\lambda x=0$ ,  $w'+\lambda x=0$ , where  $w, w' = x+iy$ .

The absolute in Euclid 9, consists, as a locus of pts, of the line at  $cs$   $x=0$  taken twice, & as an envelope of lines of two ming pencils  $w+\lambda x=0$  &  $w'+\lambda x=0$ , with their vertices on the line at  $cs$ . These two ming vertices are the pts of intersect of the pt-circle  $ww' = x^2 + y^2 = 0$  with the line at  $cs$ .

Since the eqn of any circle can be written  $ww'+u x=0$ , where  $u=0$  represents a straight line, we see that every circle passes through the two pts ( $ww'=0, x=0$ ), & for this reason these two ming pts are called the circular pts.

In Euclid 9 of 3 dim's the absolute consists general eqn of circle  $x^2+y^2+z(ax+by+c)=0$   
 $z=0$  (line at  $cs$ )  $\therefore x+iy=0, x-iy=0$  on pair of ming. lines  
 $\therefore$  any circle  $\therefore c \sim$



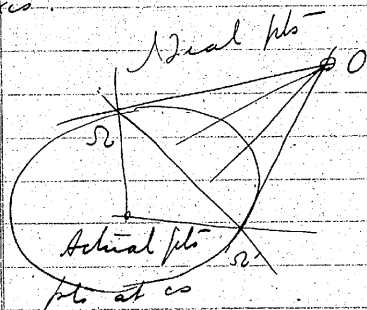
as a locus of pts, of the plane above taken twice, & as an envelope of planes, of all the planes through tangents to an imag. circle, the intersect of the pt-sphere  $x^2 + y^2 + z^2 = 0$  with the plane at  $\infty$ .

46-47

If a system of lines is such that any two are coplanar, while they do not all lie in the same plane & are neither parallel nor intersect, then they are all perpendicular to a fixed plane.

We shall call this system, which is completely determined by two of the lines, or by a certain plane  $\pi$ , a bundle of lines with an ideal vertex  $O$ .

$\pi$  axis

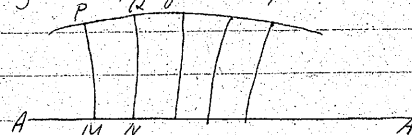


all the lines of the pencil with vertex  $O$   
 $\perp R-R'$

circle = locus of pts at a constant dist from a fixed pt. A circle cuts all its radii at  $\perp$ , orthogonal trajectory of a pencil of lines with a real vertex.

Let the vertex go to  $\infty$ ; then the lines of the pencil become  $\parallel$ , & the circle takes a limiting form, which is not, as ordinary geom., a straight line, but is a uniform curve. This curve, a circle with  $\infty$  radius, is called a horocycle; it is the orthogonal trajectory of a pencil of parallel lines. All horocycles are superposable.

orthog. traj. of lines of pencil with ideal vertex



equidistant curve

circle = i.e. {	circle	-	sphere
	horocycle	-	horosphere
	equi-dist. c.	-	equi-dist. surf.
plane cut of sphere	- - -	circle	
of horosph.	- - -	circle, except when the cut is normal to the surface	
		horocycle	
		plane = axial pt. of sphere & circle	
of equi-dist. surf.	- - -		circle & equi-dist. curve

Geom. of a bundle of lines + planes.

In plane g. we have pts, lines, dist. + angles; a bundle of lines + planes through a pt O we have lines, planes, plane angle & dihedral angle. Let us change the language to make it resemble the lang. of plane g. In translating from one lang. to another we require a dictionary. The following will suffice.

- "Point" - - - line through O
  - "Line" - - - plane through O
  - "Dist. between two pts" - length betw. two lines through O
  - "Angle betw. two lines" - dihedral angle betw. two planes thru O
  - "Parallel lines" - Parallel planes
- The two "pts" determine a "line" + two "lines" determine a "pt." "Parallel lines" only exist when O is at cs or ideal.

When O is at cs, through a given "pt" there passes just one "line" "parallel" to a given "line"; + when O is ideal, two "parallels" can be drawn through a given "pt" to a given "line".

There are three kinds of geom. of a bundle according as the vertex O is actual, at cs or ideal, & these are exactly of the same form as elliptic, parabolic (i.e. euclid.) & hyperbolic plane geom.

If a sphere be drawn with centre O cutting

the lines + planes of the bundle, we can get a further correspondence. When O is an actual pt. we have a proper sphere. We have the following dictionary:

- "Point" - Pair of antipodal pts on sphere
- "Line" - Great circle
- "Dist" - Length of arc
- "Angle betw. lines" - Angle betw. great circles

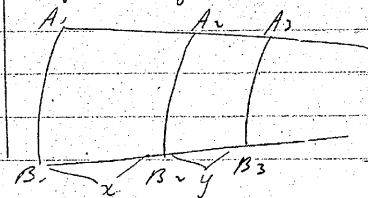
Hence the geom. on a proper sphere, where great circles represent lines, + pairs of antipodal pts represent pts, is the same as ellipt. g.

When O is ideal, the sphere becomes an equidist. surface, its geom. is hyperbolic, when O is at cs it becomes a horosphere, + its geom. is euclidean. "pt." in each case being represented by a pt. + "line" by normal sections, which are also shortest lines or geodesics on the surface.

We have here the important + remarkable theorem that the geom. on the horosphere is euclid.

57-58

Ratio of arcs of concentric horocycles



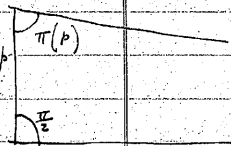
$$\frac{A_1 B_1}{A_1 B_2} = f(x) \quad \frac{A_2 B_2}{A_2 B_3} = f(y)$$

$$\frac{A_1 B_1}{A_1 B_3} = f(x+y) = f(x)f(y)$$

$$f(x) = c^x \quad c \text{ absolute constant}$$

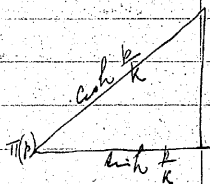
$f(x)$ , pure ratio  $\log f(x)$  or  $x \log c$  pure ratios  
 $\log c = \frac{1}{k}$   $f(x) = e^{\frac{x}{k}}$

$k$ , absolute linear curv. space-constant  
 $k$  is the length of the arc of a horocycle which is such that the tangent at one extremity is  $\parallel$  to the radius through the other extremity

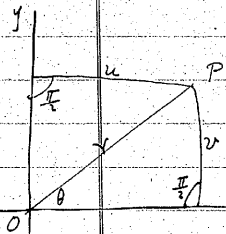


$$\tan \frac{1}{2} \pi(p) = e^{-\frac{p}{k}}$$

$$\cot \frac{1}{2} \pi(p) = \sinh \frac{p}{k}$$



§7-58



homogeneous coord.

$$x = k \sin \frac{u}{k} = k \sin \frac{y}{k} \cos \theta$$

$$y = k \sin \frac{v}{k} = k \sin \frac{y}{k} \sin \theta$$

$$z = \cos \frac{y}{k}$$

Weierstrass' point coord.

$$(hyp. 9. 2. 3. - k^2 \sin^2 \frac{y}{k} - z^2 = -k^2 = -r^2)$$

$$x^2 + y^2 - k^2 z^2 = 0 \text{ real absolute}$$

$$+ k^2 z^2 = 0 \text{ imag. absol. ellip. g.}$$

ideal pts (outside the absolute), ultrainfinite

Hilbert's axiom,  $\frac{1}{2}$  in  $ds^2$  (line element)  $ds^2 = dx^2 + dy^2 + dz^2$  homog. eq. of 2nd ds.  
 $(\text{free mobil. } \cdot \text{homodromy } \cdot)$   $ds = \sqrt{dx^2 + (1 + \frac{1}{4} dx^2)}$   $d = \frac{1}{k}$   $\cdot$   $\text{invs } + c$

- 4 Periods of  $\mathbb{R}^n$  - dim.  $n$
- |                     |  |
|---------------------|--|
| 1. synth. elem. $n$ | Gauss, Lobat, Bolza                              |
| 2. geodesic repr.   | Poinc. Helm. Lie, Klein                          |
| 3. proj. repr.      | Cayley, Wele                                     |
| 4. hyp. cal. group  | (Standl.), Pasch, Hilbert, Peano, Poinc. Viellan |

Starting with the group of proj. transf., we determine the character of the transformations so that this axiom of free mobility in the infinitesimal may be verified. We prove that they form a group which leaves unaltered either a non-ruled surface of the 2nd degree (real or imag. ellipsoid, hyperboloid of two sheets or ellip. paraboloid), or a plane & an imaginary conic lying on this plane. This invariant figure is just the Absolute. The motions of space, form a subgroup of the general proj. group of  $kt$ -transf. which leave the Absolute invariant. And so, without ~~the~~ Hilbert's axiom of homodromy, but using a definite assumption of free mobility, we establish that the only possible types of metrical groups are the 3 types in which the Absolute is a real non-ruled quadric (hyp. 9), an

imaginary quadric (elliptic) & a plane with a  
imaginary line (Euclid 9) 198-199

### Assumpt of coord.

There are several pts on which the investigation of Klein & Lie admit of criticism. The outstanding difficulty which strikes one at the once lies in the use of coord. How can we define the coord of a pt before we have fixed the idea of congruence? This quest has been settled by appeal to the famous procedure of von Staudt. He has shown (Geom 2 Logic & Rhetoric 3. 4. 2. 2.) how by means of repeated application of the quadrilateral construction for a harmonic range, no. 3 can be assigned to all the pts of a line. This, & other questions involved, have now been solved by the modern procedure of Papp, Hilbert & the Italian school represented by Peirce. This procedure which marks a return to the classical method of Euclid consists in developing geom as a purely logical system deduced from a appropriately chosen system of axioms or assumptions.

space dim = 4 & 3 in axis 19 & 1. 1917 = 1918

no. of dim. & curvature of space is of arbitrary origin. While the concept of non-eucl. space of 3 dim. in no way implies necessarily space curvature of or a fourth dim. it is still an interesting speculation to suppose that we exist really in a space of 4 dim. but with our experience confined to a certain curved locus in this space, just as Helmholtz's "two-dimensional beings" were confined to the surface of a sphere in space of three dim., & acquired in this way the idea that this geom. is non-eucl.

W. K. Clifford (The American Journal of Science 4. 1. 1870. 8. 19.) has gone further than this & imagined that the phenomena of electricity etc. might be explained by periodic vibrations in the curvature of space. But we cannot now say that this three dim. universe in which we have our experience is space in the old sense, for space, as distinct from matter, consists of a changeable set of terms or changeable rel's. There are two alternatives. We must either conceive that space is really of four dim. & our universe is an extended sheet of matter existing in this space, the latter if we like; & the, just as a plane surface is to our 3-dimensional intelligence a pure abstract, so our whole universe will become an ideal abstract existing only in a

mind that perceives space of four dim - an argument which has been brought to the support of Bishop Berkeley! (Histor. Scientific Revue, Paris, p. 31; - the 4th dim) Or, we must resist our innate tendencies to separate out space & bodies as distinct entities, & attempt to build up a scientific theory of the physical world in terms of a single set of entities, material pts. conceived as altering their sets with time (Whitehead, Gen. math. concepts of the real world). In either case it is not space that is altering its qualities, but matter which is changing its form or sets with time.

200-201

Subst. of End. representat.  $5 \times 3 \times 3 \times 3$   
Beltrami to geom. consisting in  $3 \times 3 \times 3 \times 3$   
He shows absolute test of consistency.  $3 \times 3$

Pure visual space, which is the limited field of our imaginary one-eyed astatic philosopher, is a curved elliptic two-dim space

These astronomical experiments are based upon the received laws of astronomy & optics.

which are themselves based upon the euclidean assumption. It might well happen, then, that a discrepancy observed in the sum of the angles of a triangle could admit of an explanation by some modification of these laws, or that even the absence of any such discrepancy might still be compatible with the assumption of non-euclidean geom. (paradox)

209

"All measurement involves both physical & geom. assumptions, & the two things, space & matter, are not given separately, but analysed out of a common exp. Subject to the general condition that space is to be changed & matter to move about in space, we can explain the same observed results in many different ways by making compensatory changes in the qualities that we assign to space & the qualities we assign to matter. Hence it seems theoretically impossible to decide by any experiment what are the qualities of one of the in distinct from the other." (Broad,  $\frac{1}{2}$  3:10-12)

209-10

The conclusion thus arrived at by Poincaré is quite akin to the modern doctrine in physics expressed by the Paragraph of Relativity. Just as, according to this doctrine, it is impossible by any means to obtain a knowledge

If absolute rest, as accord. to Poincaré, it is beyond  
our power to obtain a knowledge of absolute space.

210





Co.  
Th  
9